



aerospace climate control electromechanical filtration fluid & gas handling hydraulics pneumatics process control sealing & shielding





## **HLE Linear actuators**

Toothed Belt- / Rack-and-Pinion Drive





ENGINEERING YOUR SUCCESS.

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## Parker Hannifin

The global leader in motion and control technologies and systems

#### **Global Partnerships Global Support**

Parker is committed to helping make our customers more productive and more profitable through our global offering of motion and control products and systems. In an increasingly competitive global economy, we seek to develop customer relationships as technology partnerships. Working closely with our customers, we can ensure the best selection of technologies to suit the needs of our customers' applications.

#### Electromechanical **Technologies for High Dynamic Performance** and Precision Motion

Parker electromechanical technologies form an important part of Parker's global motion and control offering. Electromechanical systems combine high performance speed and position control with the flexibility to adapt the systems to the rapidly changing needs of the industries we serve.

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#### **Parker Hannifin Corporation**

With annual sales exceeding \$12 billion, Parker Hannifin is the world's leading diversified manufacturer of motion and control technologies and systems, providing precision-engineered solutions for a wide variety of commercial, mobile, industrial and aerospace markets. The company employs more than 62,000 people in 48 countries

around the world. Parker has increased its annual dividends consecutive years, among the top five longest-running dividendincrease records in the S&P 500 index. For more information, visit the company's web site at www.parker.com, or its investor www.phstock.com.

paid to shareholders for 52 information site at



## **Electromechanical Automation**

Global products with local manufacturing and support

#### **Global Product Design**

Parker Hannifin has more than 40 years' experience in the design and manufacturing of drives, controls, motors and mechanical products. With dedicated global product development teams, Parker draws on industry-leading technological leadership and experience from engineering teams in Europe, North America and Asia.

#### **Local Application Expertise**

Parker has local engineering resources committed to adapting and applying our current products and technologies to best fit our customers' needs. Parker's engineering resources also extend to the development and manufacture of complete systems for continuous process and motion control applications.

#### Manufacturing to Meet Our Customers' Needs

Parker is committed to meeting the increasing service demands that our customers require to succeed in the global industrial market. Parker's manufacturing teams seek continuous improvement through the implementation of lean manufacturing methods throughout the process. We measure ourselves on meeting our customers' expectations of quality and delivery, not just our own. In order to meet these expectations, Parker operates and continues to invest in our manufacturing facilities in Europe, North America and Asia. This allows us to minimize transportation time and cost and to be able to respond more quickly to customer needs.

#### Worldwide Electromechanical Automation Manufacturing Locations

#### **Europe** Littlehampton, United Kingdom Dijon, France Offenburg, Germany Milan, Italy

**Asia** Shanghai, China Chennai, India

#### North America

Charlotte, North Carolina Rohnert Park, California Irwin, Pennsylvania Wadsworth, Ohio Port Washington, New York New Ulm, Minnesota



Offenburg, Germany



Littlehampton, UK

## Local Manufacturing and Support in Europe

Parker provides sales assistance and local technical support through a group of dedicated sales teams and a network of authorized technical distributors throughout Europe. For contact information, please refer to the Sales Offices on the back cover of this document or visit www.parker.com.



Manufacturing

O Parker Sales Offices

Distributors



Dijon, France

## Solutions to Improve Productivity, Increase Flexibility and Save Energy

## **Process Productivity and Reliability**

Parker brings together the technology and experience required for continuous process applications across many industries. AC and DC variable speed drive products combined with application-specific function block-based configuration software ensure precise speed control and reliable performance. Parker combines more than 30 years of application experience with a global sales and support network that help you increase your machine availability.



| C Drives | C Drives | irect Drive<br>otors  | Servo Drives<br>and Motors  |
|----------|----------|---|---|
| Ā        | Ō        | ΩΣ  | ਡ ਨ   |
| 1        | 1        |   | 1   |
| 1        | 1        | 1   | 1   |
| 1        | 1        | 1   | 1   |
|          |          |   |   |
| 1        |          | 1   |   |
| 1        |          | 1   | 1   |
| 1        |          | 1   | 1   |
|          |          |   |   |
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|          |          | J    J      J | I  I    I |

## Energy Efficiency and Clean Power

Parker has developed the technology to maximize the efficient use of energy in industrial, mobile and infrastructure environments.

#### Hybrid Vehicle Technology

Parker has adapted its electric drive technologies for use in hybrid electric vehicles, including utility vehicles and passenger vehicles. Examples include inverters and motor drives, as well as electric drive motors.

#### Energy Savings for Pumps, Fans and Compressors

Parker has the drive technology to help you make significant energy savings in the operation of pumps, fans and compressors in both industrial and infrastructure applications, including:

- Commercial refrigeration
- Water and wastewater treatment
- Building automation
- Industrial processes
- Hydraulic systems



*ω* ...

Power Generation and Conversion

Using proven inverter technology, Parker has developed numerous solutions for the conversion of energy for commercial use from a variety of sources, including wind, wave and energy storage devices.

## **Motion Control** Systems for **Total Production Flexibility**

Parker's electromechanical automation customers enjoy total production flexibility in their general and precision motion control applications. Complete packaged linear positioning systems, coupled to servo and stepper drives and controls, enable our customers to develop a complete motion solution with one partner. Parker provides the products for a wide range of motion needs- power, speed, travel, forcewith easy to use controls designed to work on multiple control and communication platforms. Additionally, Parker's products can be easily customized to suit specific applications.



| Assembly machinery               | Mechanical<br>Actuators | Motors and<br>Gearheads | Drives | Controls | IWH    |
|----------------------------------|-------------------------|-------------------------|--------|----------|--------|
| Pick and place                   | 1                       | 1                       | 1      | 1        | J      |
| Lifting                          | ·<br>·                  | 1                       | 1      |          |        |
| Transfer machinery               | 1                       | ·<br>·                  | 1      |          | 1      |
|                                  |                         |                         |        |          |        |
| Automotive assembly              |                         |                         |        |          |        |
| Resistance welding               | 1                       | 1                       | 1      | 1        |        |
| Painting applications            | 1                       | 1                       | 1      | 1        | 1      |
| Transfer machinery               | 1                       | 1                       | 1      | 1        | 1      |
| Packaging machinery              |                         |                         |        |          |        |
| Primary, secondary, tertiary     | 1                       | 1                       | 1      | 1        | 1      |
| Handling machinery               | 1                       | 1                       | 1      | 1        | 1      |
|                                  |                         |                         |        |          |        |
| Food processing machinery        | ,                       | ,                       | ,      | ,        |        |
| Processing machinery             | 5<br>5                  | 5<br>5                  | ۲<br>۲ | <i>J</i> |        |
| Packaging machinery              |                         |                         |        |          | ,      |
| Handling machinery               | 1                       | 1                       | 1      | 1        | 1      |
| Material handling systems        |                         |                         |        |          |        |
| Transfer systems                 | 1                       | 1                       | 1      | 1        | 1      |
| Pick and place systems           | 1                       | 1                       | 1      | 1        | 1      |
| Metal forming machinery          |                         |                         |        |          |        |
| Presses                          | 1                       | 1                       | 1      | 1        | 1      |
| Tube bending                     | ·<br>·                  | ,<br>,                  | ·<br>· |          | ·<br>· |
| Handling applications            | ·<br>·                  | 1                       | ·<br>· |          | 1      |
|                                  |                         |                         | •      |          |        |
| Machine tools                    |                         |                         |        |          |        |
| Spindles                         |                         | 1                       | 1      |          |        |
| Ancillary axes                   |                         | 1                       | 1      |          |        |
| Semiconductor machinery          |                         |                         |        |          |        |
| Front end processes              | 1                       | 1                       | 1      | 1        | 1      |
| Inspection machinery             | 1                       | 1                       | 1      | 1        | 1      |
| Packaging machinery              | 1                       | 1                       | 1      | 1        | 1      |
| Lithography                      | 1                       | 1                       | 1      | 1        |        |
|                                  |                         |                         |        |          |        |
| Medical devices                  |                         |                         |        |          |        |
| Device manufacturing             | 1                       | 1                       | 1      | 1        | 1      |
| Product packaging and dispensing | 1                       | 1                       | 1      | 1        | 1      |
| Scanning equipment               | 1                       | 1                       | 1      |          |        |
| Pumps and analyzers              |                         | 1                       | 1      |          |        |
| Entertainment                    |                         |                         |        |          |        |
| Theatre and studio automation    | 1                       | 1                       | 1      | 1        |        |
| Simulation and amusement rides   | 1                       | 1                       | 1      |          |        |
|                                  |                         |                         |        |          |        |

## **Complete Range of Solutions**



#### Remote I/O











**Gantry Systems** 

## Value Added Services

In addition to providing products and systems, Parker also provides a number of value added services to our customers:

- Programming and commissioning services
- Power quality and energy surveys
- 24-hour support and service
- Product repairs
- Product training

## Customization

Many automation applications cannot be solved with off the shelf products. Parker's products are designed to be versatile as well as easy to configure for the majority of industrial and process applications. Some customers require solutions that can't be found in a catalogue, and Parker has the resources and expertise available to provide customized solutions:

- Custom motor designs
- Customized mechanical positioning systems
- Customized control functionality
- Customized communication solutions





## System Solutions

Parker offers system design and manufacturing in two main categories:

#### **Drive Systems**

Complete AC and DC drive systems across a wide power range, from less than 1 kW to more than 1 MW. Systems typically include electrical enclosure, ancillary electronic equipment and full documentation. Commissioning and support services are standard.

#### **Mechanical Systems**

Parker has more than 20 years of experience in providing a variety of multiple axis mechanical positioning systems, complete with motors, drives and controls. Typical applications include material transfer and pick and place gantry systems. Additionally, Parker designs and builds custom precision positioning systems, integrating precision bearing, feedback and drive systems, including Parker's range of linear servo motors. Each system ships complete with motors, drives and controls, and can include the programming and commissioning.

## **Parker Linear Actuators**

Benefits of Parker Linear Actuators

A part of Parker's mechanical components comprises linear actuators, vertical actuators, telescopic actuators and screw actuators, which are all based on an aluminum profile. Depending on the load, several types with different profile cross-sections are available. The carriages run either on sliding bearings, on plasticsheathed rollers or steel rollers. As drive options, ballscrew drives, conventional toothed belt drives or a combination of toothed belt and rackand-pinion-drive are available.

#### Toothed belt drive with rollers

HPLA, HLE Linear Actuators www.parker-eme.com/hpla www.parker-eme.com/hle



For high dynamics at small to medium stroke lengths. Plastic sheathed rollers, optionally steel rollers, for high payloads.

## Toothed belt drive with sliding bearing

LCB Linear Actuator www.parker-eme.com/cb



Clean operation without lubricants.

#### **Rack-and-pinion drive**

HPLAZ, HLEZ Linear Actuator www.parker-eme.com/hpla www.parker-eme.com/hle



A short toothed belt runs on a tooth rack without lubrication. This ensures a consistent and high rigidity even with long strokes.

#### Linear motor principle

PowerRod, BLMA Linear Actuators www.parker-eme.com/powerrod www.parker-eme.com/blma



For highest dynamics and high precision.

#### Drive for high forces when moving in axial direction

ET Screw Actuator www.parker-eme.com/et



Ballscrew in the ET electro thrust cylinder.

## Omega drive for vertical movements

HZR Z-Axis www.parker-eme.com/hzr

## Telescopic drive for vertical movements

HTR telescopic actuator www.parker-eme.com/htr



Drive station fixed, toothed belt and profile movable together



Three-stage telescopic actuator featuring an extremely low height.

#### Accessories

A wide range of Parker accessories simplifies the integration.

#### Motors and controllers

The right gear-servomotor will, in combination with the optimal Parker servo amplifier, solve any positioning task.

#### All from one source

Our modular system allows a flexible, cost-efficient design of complex systems and plants. Please contact your local sales office for more information.

## **The HLE Series Linear Actuators**

- For Guiding, Moving and Positioning -



## The Dynamic Linear Actuator

for guiding, moving and positioning, even over long travels, we offer:

- High speeds up to 5 m/s
- Transmissible drive torque max.
  108 Nm
- Long strokes up to 20 m
- High load bearing capacity horizontal up to 1000 kg / vertical up to 300 kg
- Repeatability up to ± 0.05 mm
- High mechanical efficiency of 95 %
- Two profile sizes: LEB100 and LEB150 can be combined in a modular system
- Simple, fast mounting and commissioning

## Typical Areas of Application

within the scope of innovative and cost-effective machine and system design:

- Handling technology e.g. palletizing, material feed and removal
- Textile machine construction e.g. cross-, length cutting and stacking, quilting, seaming
- Process engineering e.g. varnishing, coating, gluing
- Stock technology e.g. commissioning, stock-keeping
- Construction technology E.g. encasing, inserting steel reinforcements into concrete
- Clean room technology e.g. wafer transport, wafer coating
- Machine tool manufacturing e.g. charging of the work pieces, changing the tools
- Testing technology e.g. guiding of ultrasonic sensors

## The Sophisticated Technology

proven in many applications offers the following advantages for your tasks:

- Frictionless motion ensures:
  - low abrasion (suitable for clean room up to class 10)
  - low wear
  - Maintenance-free operation
  - low-noise
  - high efficiency and
  - high service life
- High dynamics due to low-mass, backlash-free carriage
- Simplified inspection with long inspection intervals.
- Longitudinal grooves on all surfaces

integrated ion all sides of the profile for

mounting attachments or for us as a cable duct

- Exchange of toothed belt without dismounting of the load attachment plate
- Flexible installation options provided by longitudinal grooves in the load attachment plate

## The HLE - A Sophisticated Technology

#### The All-Purpose Actuator

The HLE linear actuator offers an appropriate solution for all motion tasks. It is ideal for use as a single axis, or as a component in a multiple axis system.

It has been developed for rapid linear movements over long stroke distances. The HLE provides a simple machine and system element and can be used without the need for any specialized knowledge. Installation and starting up only requires a small amount of effort from the user. The HLE is supplied in many different configurations with numerous options and many accessories.

#### **Our Experience**

You can trust in our experience and skill, as over 25000 actuators are already in use throughout the world be it in automatic textile equipment, handling systems, packaging machines, automatic painting and binding equipment...etc.

The HLE can be found in a wide range of applications: in clean rooms, in the food industry, production plants in the chemical industry or in the manufacture of prefabricated concrete components.

We cooperate with a wide range of different industrial sectors including the automotive industry, machine tool manufacturers, microelectronics manufacturers - and hopefully soon with you...

#### **Examples/Applications**

- Mercedes Benz, Sindelfingen: Handling cockpit parts in the S-class
- **IBM**, Böblingen: Wafer transport in chip production
- Bosch-Siemens Hausgeräte GmbH, Traunreut: Handling cookers
- SEL, Stuttgart: Picking electronic components
- Bayer, Bitterfeld: Palletizing folding cartons (flat pack boxes) for pharmaceuticals
- LT Engineering, Switzerland: Shelf-picking unit for small parts stores
- Braas, Steinfeld: Handling roof tiles
- **Philips**, Netherlands: Handling screen masks
- Weckenmann, Dormettingen: Setting shell profiles in the concrete industry.



### **HLE Drive Principle**

The HLE consists of an extruded, self-supporting aluminum profile and a carriage, which is fitted backlash-free into the profile with the aid of rollers and is moved via a timing belt.

The steel tension cords integrated into the belt provide the necessary stiffness and prevent an extension of the belt. Special toothed pulleys ensure backlashfree operation - and therefore an excellent repeatability even with long strokes at high speeds.



### Design and Function of the Optional Steel Strip Cover

The optional steel strip cover is perfectly integrated into the HLE design and protects toothed belt, rollers and the running surfaces of the profile reliably from contamination (protection class IP30).



### **Construction of the HLE**



- 100x100 mm (LEB100)
- 150x150 mm (LEB150)

All profiles feature eight lengthwise clamping grooves for the attachment of additional mechanical components and for the connection of several HLE actuators. These grooves can also be used to attach initiators and mechanical switches.

These grooves are also suitable as cable ducts if equipped with the available cover profile (8).

#### The carriage (2)

Light, rigid carriage with plastic rollers. Overall, this results in high mechanical efficiency and virtually wear-free operation. The rolling-contact plastic rollers with lifetime lubrication are aligned backlash-free in all directions via eccentric. The carriage is available in two sizes as a standard carriage with

twelve rollers or as an extended carriage with twenty-four rollers. Customer-specific special carriages are available on request.

#### The tensioning station (3)

An easily maintained and assemblyfriendly tensioning station for setting the tension required for the toothed belt and its orientation (parallelism of pulleys).

#### The drive station (4)

Robust cast casing with standard flange. Many gear reducers can be directly flange-mounted (for bore pattern, refer to dimensions). Available with drive shaft on the right, on the left or on both sides on request.

#### The toothed belt (5)

The practically backlash-free toothed belt reinforced by steel tension cords guarantees high travel speeds and repeatabilities.

#### Toothed belt clamping (6)

The toothed belt fixing bracket ensures a safe connection of toothed belt and carriage.

The clamping system allows the toothed belt to be changed without removing the load attachment plate. This means that it is in most cases not necessary to remove the mounted components.

#### The load attachment plate (7)

 Many possibilities to mount parts by integrated longitudinal grooves at the upper side of the plate. In connection with the clamping profiles (page 32), this allows an easy integration into multi-axis systems.

- Simple and variable mounting of a tripping plate due to lateral longitudinal grooves on the load attachment plate.
- The unit height and the fixing points remain unchanged even if a steel strip cover is mounted in retrospective.

Special versions are available on request.

#### The drive unit (optional) (9)

Parker servo motor and an appropriate planetary gearbox provide an optimum drive for dynamic and accurate applications.

In connection with the compact Compax3 servo drive, you can dispose of a complete, plug-in automation system for single and multi axis linear- and path control.

#### The V2A version (Material design V)

Minimized particle emissions and high levels of resistance to water and various cleaning agents make the V2A version of the HLE the number one choice for use in clean rooms or in the food industry.

The steel components are made of V2A material and the rollers and toothed pulleys are equipped with corrosion-free bearings.

## **Technical Data**

| HLE - size   |                      | 10       | 00                   | 1        | 50                   |  |  |  |
|--|----------------------|----------|----------------------|----------|----------------------|--|--|--|
|  | Unit                 | Standard | Steel strip<br>cover | Standard | Steel strip<br>cover |  |  |  |
| Weights and mass moments of inertia  |                      |          |                      |          |                      |  |  |  |
| Weight of base unit without stroke   |                      |          |                      |          |                      |  |  |  |
| HLE with standard carriage S   | [kg]                 | 11.5     | 12.7                 | 28.6     | 31.2                 |  |  |  |
| HLE with extended carriage E   | [kg]                 | 14.6     | 15.8                 | 35.9     | 38.5                 |  |  |  |
| Mass of standard carriage S<br>including load attachment plate             | [kg]                 | 2.5      | 2.8                  | 6.7      | 7.3                  |  |  |  |
| Mass of extended carriage E<br>including load attachment plate             | [kg]                 | 4.1      | 4.4                  | 10.9     | 11.5                 |  |  |  |
| Additional weight per meter of stroke                                      | [kg/m]               | 9.9      | 10.0                 | 21.0     | 21.1                 |  |  |  |
| Mass moment of inertia relative to the                                     | drive shaft          |          |                      |          |                      |  |  |  |
| Standard carriage S  | [kgcm <sup>2</sup> ] | 22.3     | 24.6                 | 114.0    | 123.3                |  |  |  |
| Extended carriage E  | [kgcm <sup>2</sup> ] | 34.1     | 36.4                 | 174.4    | 183.6                |  |  |  |
| Travel lengths and speeds  |                      |          |                      |          |                      |  |  |  |
| Maximum travel speed <sup>1</sup>  | [m/s]                | 5        | 5.0                  |          |                      |  |  |  |
| Maximum acceleration <sup>1</sup>  | [m/s²]               | 10       | ).0                  | 10.0     |                      |  |  |  |
| Maximum travel, standard carriage S/T <sup>2</sup> with one profile bar    | [mm]                 | 6300     | 6300 6210            |          | 8140                 |  |  |  |
| Maximum travel, extended carriage<br>E/F <sup>2</sup> with one profile bar | [mm]                 | 6150     | 6150 6060            |          | 7990                 |  |  |  |
| Overall dimensions & physical data   |                      |          |                      |          |                      |  |  |  |
| Cross-section  | [mm x mm]            | 100 x    | < 100                | 150      | x 150                |  |  |  |
| Moment of inertia I <sub>x</sub>   | [cm⁴]                | 38       | 33                   | 1940     |                      |  |  |  |
| Moment of inertia I <sub>y</sub>   | [cm⁴]                | 4:       | 31                   | 21       | 47                   |  |  |  |
| Moment of inertia I <sub>t</sub>   | [cm⁴]                | 1.       | 17                   | 3        | 91                   |  |  |  |
| E-modulus (aluminum)   | N/mm <sup>2</sup> ]  |          | 0.72                 | x 10⁵    |                      |  |  |  |
| Toothed pulley data, Torques, Forces u                                     |                      | су       |                      |          |                      |  |  |  |
| Travel distance per revolution   | [mm/rev]             |          | 70                   | 24       | 40                   |  |  |  |
| Diameter of pulley   | [mm]                 | 54.      | 113                  | 76.      | 394                  |  |  |  |
| Toothed belt width / pitch   | [mm]                 |          | / 10                 |          | / 10                 |  |  |  |
| Weight of toothed belt   | [kg/m]               |          | 66                   |          | 213                  |  |  |  |
| Nominal drive torque   | [Nm]                 |          | 5.7                  |          | .4                   |  |  |  |
| Maximum drive torque <sup>3</sup>  | [Nm]                 |          | 0                    |          | 08                   |  |  |  |
| Nominal belt traction force (payload)                                      | [N]                  |          | 30                   |          | 50                   |  |  |  |
| max. belt traction force <sup>3</sup> (payload)                            | [N]                  | 14       | 78                   | 28       | 27                   |  |  |  |
| Repeatability⁴<br>- up to 3 m<br>- as from 3 m                             | [mm]                 | ±0<br>±( | .05<br>).1           |          | .05<br>).1           |  |  |  |
| Efficiency   | [%]                  |          |                      | 5        |                      |  |  |  |

#### Please contact Parker if your application has the following requirements:

<sup>1</sup> Travel speeds over 5 m/s und Accelerations over 10 m/s<sup>2</sup>.

- <sup>3</sup> Increased toothed belt tension is required.
- <sup>4</sup> At a constant ambient and operating temperature of the actuator. Determined in accordance with ISO 230-2.

<sup>&</sup>lt;sup>2</sup> Longitudinal flanges for longer strokes are possible. The following constraints are to be expected with: max. permissible load, drive torque, speed, acceleration, repeatability (see page 34)

<sup>→</sup> Safety factor taken into consideration S=1. Data applies to a temperature range between -10 °C and + 40 °C

### **HLE Toothed Belt Load Bearing Capacity**



Forces and torques transferred by the carriage are speed-dependant. The graphs shown in the diagrams only apply to standard carriages (S/T). In the case of extended carriages (E or F), all values with the exception of Fx (toothed belt load bearing capacity) can be doubled if the load is introduced in pairs or is distributed evenly over the entire length of the carriage.

The curves show the maximum loadbearing capacity of a carriage in one direction of force or torque. If several loads are applied in different directions, the values specified in the curves **must be derated**, i.e. the load or speed should be reduced. For precise dimensioning, our software "DimAxes" is available (Refer to "Additional Accessories / Software", page 44).













## **Dimensional Drawings**

HLE100 - single axis (LEB100)



Dimensions in () are valid in connection with steel strip cover Components adumbrated in dashed lines: Steel strip cover option Housing excess at drive and tensioning station approx. 1 mm

#### HLE100 - drive housing with drive shafts (LEB100)



#### HLE100 - double axis with gearbox flange Q and R (LEB100)

(for flange dimensions please refer to the HLE100 dimensional drawing on page 18)







#### HLE100 - double axis with gearbox flange B (LEB100)





Center distance A between 225-500 mm



#### HLE150 - single axis (LEB150)



Dimensions in () are valid in connection with steel strip cover Components adumbrated in dashed lines: Steel strip cover option Housing excess at drive and tensioning station approx. 1 mm

#### HLE150 - drive housing with drive shafts (LEB150)



#### HLE150 -double axis with gearbox flange R (LEB150)

(for flange dimensions please refer to the HLE150 dimensional drawing on page 20)







#### HLE150 -double axis with gearbox flange R (LEB150)







### HLE - Idler Unit



The HLE is also available as a driveless idler unit. In this case, it serves as a mere guiding. The profile cross section and carriage dimensions correspond to the dimensions of the actuators.

|                 |    | Wit | hout st | eel strip cover |     | With steel strip cover |    |     |    |     |  |  |
|-----------------|----|-----|---------|-----------------|-----|------------------------|----|-----|----|-----|--|--|
| Axis type       | LD | LP  | SW*     | LU              | LL  | LD                     | LP | SW* | LU | LL  |  |  |
| LEN100S/LEN100T | 10 | 24  | 125     | not applicable  | 300 | 10                     | 69 | 125 | 35 | 300 |  |  |
| LEN100E/LEN100F | 10 | 24  | 120     | not applicable  | 450 | 10                     | 09 | 125 |    | 450 |  |  |
| LEN150S/LEN150T | 10 | 36  | 125     | not applicable  | 350 | 10                     | 04 | 125 | 35 | 350 |  |  |
| LEN150E/LEN150F | 10 | 30  | 125     | not applicable  | 500 | 10                     | 81 | 125 |    | 500 |  |  |

\* SW = safety travel

### **Carriage with Bar**

(Carriage T/F without load attachment plate; thread drawings for mounting the load)

For an HLE without load attachment plate, a bar is required as a replacement for the belt clamping. In order to attach your own loads, the threads in the carriage are accessible through bores in the strip.

#### HLE standard carriage with bar ((LEB100T/LEN100T)



#### HLE extended carriage with bar (LEB100F/LEN100F)



#### HLE standard carriage with bar (LEB150T/LEN150T)



#### HLE extended carriage with bar (LEB150F/LEN150F)



# The HLEZ150 Linear System with Rack-and-Pinion Drive

- for long travels with consistently high stiffness and precision



#### The "unlimited" linear actuator

for guiding, moving and positioning, even over long travels, we offer:

- Long travels up to 50 m
- High speeds in practice up to 5 m/s
- High load bearing capacity horizontal up to 1000 kg / vertical up to 300 kg
- Transmissible drive torque max. 32 Nm
- Repeatability up to ± 0.05 mm
- Several carriages on a single actuator are possible
- Simple, fast mounting and commissioning

#### Typical areas of application

within the scope of innovative and cost-effective machine and system design:

- Handling technology e.g. palletizing, material feed and removal
- Textile machine construction e.g. cross-, length cutting and stacking, quilting, seaming
- **Process engineering** e.g. varnishing, coating, gluing
- Stock technology e.g. commissioning, stock-keeping
- Construction technology e.g. encasing, inserting steel reinforcements into concrete
- Clean room technology e.g. wafer transport, wafer coating
- Machine tool manufacturing e.g. charging of the work pieces, changing the tools
- Testing technology e.g. guiding of ultrasonic sensors

#### The combined technology

of the HLE linear actuator and rack offers the following advantages:

- High dynamic response, even over long travel distances, due to:
  - the short toothed belt
  - regardless of travel length
  - the lightweight carriage the backlash free drive
  - the backlash free drive
- High positional accuracy regardless of stroke length
- Option of several carriages per linear actuator, making overlapping strokes along a single actuator possible
- Long inspection cycles, simple inspection
- Grooves running in the profiles on all sides to enable
- mounting of the HLEZ to a supporting structure, fitting attachments or as cable ducts
- Flexible installation options provided by longitudinal grooves in the load attachment plate.

### The HLEZ - A Combined Technology

#### The new design

Taking the HLE linear actuators as its base, a new rack-and-pinion drive system has been designed for the LEB150.

The system which is especially suitable for long travel distances and high speeds, opens up a whole range of new applications options. The patented rack principle permits "endless" travel whilst maintaining high accuracy. At the same time, the dynamic characteristics of the system are outstanding.

When required, several carriages can be positioned on a single actuator independently of each other. In combination with other Parker mechanical components, this allows the construction of efficient and cost-effective gantry and automation systems.

#### **Our experience**

You can rely on our experience and skill, as over 25000 linear actuators are already in use throughout the world - whether it be in automatic textile equipment, handling systems, packaging machines, automatic painting and binding equipment, etc... The HLEZ is found across a broad application area - in clean rooms, in the food industry, in chemical production plants and in the production of precast concrete components. We cooperate with a wide range of different industrial sectors including the automotive industry, machine tool manufacturers, microelectronics manufacturers - and hopefully soon with vou...

#### **Examples/applications**

- Sick, Waldkirch: Sensor testing equipment
- **Desarrollo**, Spain: Gantry robots for transporting glass fiber coils
- Springs, USA: Sewing textiles
- Weckenmann, Dormettingen: Wide-area gantry robots for the precast-concrete industry
- AZO, Osterburken: Marshalling equipment
- **EEW**, Schönberg: High-speed milling center
- **Telecom**, Switzerland: Telephone accessory order picking system
- LT Engineering, Switzerland: Shelf-picking unit for small parts stores
- Allied Signal, USA: Sewing airbags
- Weber-Haus, Linx: Boring and sawing cut-outs for the mounting of distribution boxes and socket outlets

#### **HLEZ - Drive Principle**

The HLEZ drive offers all the advantages of a toothed belt drive, without its typical disadvantages. The consistently short toothed belt, which is independent of the travel stroke, reduces belt stretch to a minimum. The lateral deflection rollers pretension the system and eliminate the backlash. Contact rollers ensure that a sufficient number of teeth are in contact with the pulley. The combination of plastic timing belt with an aluminum rack is a safe and clean drive which does not require lubrication.



## All of this offers the following advantages:

- high, consistent stiffness independent of the stroke length or position
- very long strokes are possible
- high precision
- high speeds are possible
- smooth, low-noise running
- no lubrication required
- any installation position possible

#### Construction of the HLEZ150



#### The profile (1)

Light, compact and self-supporting construction made from an aluminum profile.

The profile features seven lengthwise clamping grooves for the attachment of additional mechanical components and for the connection of several HLEZ and HLE actuators. These grooves can also be used to attach initiators and mechanical switches. Together with the cover profile (2), these can be used as cable ducts.

#### The carriage (3)

Lightweight, rigid carriage with rolling-contact plastic bearings (4) and eccentric axes for a backlashfree alignment of the carriage in all directions. Overall, this results in high mechanical efficiency and virtually wear-free operation. The carriage can be supplied in two lengths either standard or extended. Customer-specific special carriages are available on request.

#### The load attachment plate (5)

Many possibilities to mount parts by integrated longitudinal grooves at the upper side of the plate. In connection with the clamping profiles (page 33), this allows an easy integration into multi-axis systems.

Simple and variable attachment of operating cams or switch lugs is provided by longitudinal grooves placed on the sides or underneath the plate. Special versions are available on request.

#### The drive module (6)

Compact drive module, can be optionally supplied fitted on either side of the load attachment plate. Description of the drive principle: see on page 25

Parker servo motor (7) with resolver and appropriate planetary gearbox form the optimum drive for dynamic and precise applications. In connection with the compact Compax3 servo drive, you can dispose of a complete, plug-in automation system for single and multi axis linear- and path control.

## **Technical Data**

| HLEZ - Size   | Unit                 | 150                              |
|---|----------------------|----------------------------------|
| Weights and mass moments of inertia   |                      |                                  |
| Weight of base unit without stroke  |                      |                                  |
| HLEZ with standard carriage   | [kg]                 | 53                               |
| HLEZ with extended carriage   | [kg]                 | 61                               |
| Mass of standard carriage load attachment plate and drive module                      | [kg]                 | 25.7                             |
| Mass of extended carriage with load attachment plate and drive module                 | [kg]                 | 29.7                             |
| Mass per meter of additional length (guiding profile + rack)                          | [kg/m]               | 23.9                             |
| Mass moment of inertia with respect to the drive shaft1 (taken into consideration: ca | arriage with load at | tachment plate and drive module) |
| Standard carriage S   | [kgcm <sup>2</sup> ] | 325                              |
| Extended carriage E   | [kgcm <sup>2</sup> ] | 363.4                            |
| Strokes, travel speeds and efficiency   |                      |                                  |
| Maximum travel speed  | [m/s]                | 5.0                              |
| Maximum stroke, standard carriage S/T <sup>2</sup> with one profile                   | [mm]                 | 8888                             |
| Maximum stroke, extended carriage E/F <sup>2</sup> with one profile                   | [mm]                 | 8738                             |
| Maximum stroke with longitudinal flange(s) <sup>3</sup>                               | [mm]                 | 50000                            |
| Efficiency  | [%]                  | 85                               |
| Overall dimensions and physical data of guiding profile                               |                      |                                  |
| Cross-section   | [mm x mm]            | 150 x 150                        |
| Moment of inertia I <sub>x</sub>  | [cm⁴]                | 1940                             |
| Moment of inertia I <sub>v</sub>  | [cm⁴]                | 2147                             |
| Moment of inertia I,  | [cm⁴]                | 391                              |
| E-modulus (aluminum)  | N/mm²]               | 0.72 x 10⁵                       |
| Pulley data, torques and forces   |                      |                                  |
| Travel distance per revolution  | [mm/rev]             | 200                              |
| Pulley diameter of drive pinion (D <sub>A</sub> )                                     | [mm]                 | 63.66                            |
| Number of teeth of drive pinion   |                      | 20                               |
| Toothed belt width/pitch  | [mm]                 | 50 / 10                          |
| Drive torque  | [Nm]                 | 32                               |
| Thrust force  | [N]                  | 1000                             |
| Repeatability <sup>4</sup>  | [mm]                 | ± 0.05                           |



Please contact Parker if your application has the following requirements!

 $^{1}$  Additional mass moment of inertia caused by the payload: J  $_{\text{payload}}$  =  $m_{\text{payload}}$  x 1/4 DA2

(motor and gear weight are added to the payload).

<sup>2</sup> Longitudinal flanges possible in order to obtain longer strokes (see on page 34).

<sup>3</sup> The travel is unlimited by the linear actuator - it depends however on the energy supply of the drive.

<sup>4</sup> Applies for the linear actuator with drive module, without drive.

→ Safety factor taken into consideration S=1. Data applies for a temperature range of between -10°C and +40°C

#### **HLEZ Toothed Belt Load Bearing Capacity**



Forces and torques transferred by the carriage are speed-dependant. The graphs shown in the diagrams only apply to standard carriages (S/T). In the case of extended carriages (E/F), all values can be doubled if the load is introduced in pairs or evenly over the entire length of the carriage. The curves show the maximum load-bearing capacity of a carriage in one direction of force or torque. If several loads are applied in different directions, the values specified in the curves **must be derated**, i.e. the load or speed should be reduced if necessary. For precise dimensioning, our software "DimAxes" is available (calculation identical to HLE150) (see "Other Accessories / Software" on page 44).















## HLEZ150 Dimensional Drawing

#### **Gearbox fitting - Examples**

HLEZ150 with planetary gearbox PL5-OP11 or PE5 (LEZ150)





|                   |                | PL5 C     | OP 11     |           |           |             |
|-------------------|----------------|-----------|-----------|-----------|-----------|-------------|
|                   |                | one stage | two stage | one stage | two stage | three stage |
|                   | В              | 115 x 115 | 115 x 115 | Ø 115     | Ø 115     | Ø 115       |
| i                 | L              | 123.5     | 267.5     | 146.5     | 173.5     | 200.5       |
| e of transmission | i <sup>1</sup> | 3 - 10    | 12 - 100  | 3 - 8     | 9 - 64    | 60 - 512    |

#### HLEZ150 with worm gearbox (LEZ150)



## Accessories

Dimensions in [mm] Schematic representation

### Assembly Angle Plate

The assembly angle plate is used to attach a HLE or a HLEZ

- to another linear actuator
- with a base (a Parker profile can be used as support)
- to other machine components

It is available in different sizes, isosceles or scalene - each with through holes.

#### Assembly angle plate isosceles



| Frame size    | Туре        | A1 | A2 | В   | B1  | <b>B2</b> | D  | LA1 | LA2 | SD | Art. No.   |
|---------------|-------------|----|----|-----|-----|-----------|----|-----|-----|----|------------|
| LEB100        | MWD 90/90   | 20 | 30 | Ø9  | 88  | 90        | 10 | 60  | 50  | 10 | 500-000512 |
| LEB150/LEZ150 | MWD 140/140 | 30 | 40 | Ø11 | 138 | 140       | 15 | 90  | 80  | 12 | 500-000523 |

#### Assembly angle plate scalene



| Frame size    | Туре        | <b>A1</b> | A2 | <b>A3</b> | <b>A</b> 4 | <b>A5</b> | <b>A6</b> | <b>A7</b> | BO  | B1  | <b>B2</b> | <b>B</b> 3 | D  | LA1 | SD | Art. No.   |
|---------------|-------------|-----------|----|-----------|------------|-----------|-----------|-----------|-----|-----|-----------|------------|----|-----|----|------------|
| LEB100        | MWD 90/190  | 20        | 30 | 80        | 120        | 180       |           | 80        | Ø9  | 88  | 90        | 190        | 10 | 60  | 10 | 500-000513 |
| LEB150/LEZ150 | MWD 140/290 | 30        | 40 | 120       | 180        | 270       | 55        | 120       | Ø11 | 138 | 140       | 290        | 15 | 90  | 12 | 500-000524 |

## T-Nuts/Bolts

The T nuts and bolts can be used to attach other components in the T-slots of the profile, or on the upper side of the load attachment plate.



| Frame size      |           | Designation      | Α               | D    | Е     | E1    | H1      | Κ        | L  | Art. No. (stainless)    |
|-----------------|-----------|------------------|-----------------|------|-------|-------|---------|----------|----|-------------------------|
| LEB100          | T-Bolt    | DIN787 M8x8x25   |                 | M8   | 13    | 13    |         | 6        | 25 | 131-700001              |
| LEB100          | T-Bolt    | DIN787 M8x8x32   |                 | M8   | 13    | 13    |         | 6        | 32 | 131-700002 (135-725450) |
| LEB100          | T-Bolt    | DIN787 M8x8x40   |                 | M8   | 13    | 13    |         | 6        | 40 | 131-700003              |
| LEB150 / LEZ150 | T-Bolt    | DIN787 M10x10x25 |                 | M10  | 15    | 15    |         | 6        | 25 | 131-700007 (135-725459) |
| LEB150 / LEZ150 | T-Bolt    | DIN787 M10x10x32 |                 | M10  | 15    | 15    |         | 6        | 32 | 131-700008 (135-725460) |
| LEB150 / LEZ150 | T-Bolt    | DIN787 M10x10x40 |                 | M10  | 15    | 15    |         | 6        | 40 | 131-700009 (135-725465) |
| LEB150 / LEZ150 | T-Bolt    | DIN787 M10x10x63 |                 | M10  | 15    | 15    |         | 6        | 63 | 131-700011              |
| LEB100          | T-Bolt    | DIN508 M6x8      | 8               | M6   | 13    | 13    | 10      | 6        |    | 131-700103 (135-725400) |
| LEB150 / LEZ150 | T-Bolt    | DIN508 M8x10     | 10              | M8   | 15    | 15    | 12      | 6        |    | 131-700104 (135-725402) |
| LEB100          | Long nut* | HWN313 M6x8      | 8               | M6   | 13    | 26    | 10      | 6        |    | 131-700140              |
| LEB150 / LEZ150 | Long nut* | HWN313 M8x10     | 10              | M8   | 15    | 30    | 12      | 6        |    | 131-700141 (135-725406) |
| LEB100          | Nut       | ITEM St M6       | without drawing |      |       |       |         |          |    | 400-00033 (400-00032)   |
| LEB150 / LEZ150 | Nut       | HWN314 M8x10     | R               | homb | us fo | rm fo | r retro | o-fittir | ng | 131-700155              |

\* When using the combination of two linear actuators via clamping profiles, we would recommend the use of long nuts.

## Toe Clamp

The toe clamps are used in conjunction with the standard load attachment plate to rapidly install and attach various combinations of linear actuators. Two clamping profiles are needed to fix a HLE/HLEZ/HPLA on a flange plate. The following table shows the required profiles for the different axis combinations:

| top<br>bottom | LB080<br>(HPLA80)   | LE100<br>(HLE100)   | LB120<br>(HPLA120)  | LE150<br>(HLE150)   | LB180<br>(HPLA180)  |
|---------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| LB080         | Art. No. 500-000931 |                     |                     |                     |                     |
| LE100         | Art. No. 500-000932 | Art. No. 500-000905 |                     |                     |                     |
| LB120         | Art. No. 500-000930 | Art. No. 500-000908 | Art. No. 500-000925 |                     |                     |
| LE150         |                     | Art. No. 500-000903 | Art. No. 500-900909 | Art. No. 500-000902 |                     |
| LB180         |                     |                     | Art. No. 500-000922 | Art. No. 500-000921 | Art. No. 500-000920 |



| Art. No.   | A1 | A2   | В    | B1 | D  | D1 | D2  | L   | LA1      | Т    |
|------------|----|------|------|----|----|----|-----|-----|----------|------|
| 500-000902 | 25 | 12   | 40   | 25 | 30 | 15 | 9   | 140 | 90 ±0.2  | 9    |
| 500-000903 | 25 | 10   | 30   | 20 | 20 | 15 | 9   | 140 | 90 ±0.2  | 9    |
| 500-000905 | 15 | 10   | 30   | 20 | 20 | 11 | 6.6 | 90  | 60 ±0.2  | 7    |
| 500-000908 | 20 | 10   | 30   | 20 | 20 | 15 | 9   | 110 | 70 ±0.2  | 9    |
| 500-000909 | 25 | 12.5 | 37.5 | 25 | 26 | 15 | 9   | 140 | 90 ±0.2  | 9    |
| 500-000920 | 30 | 15   | 45   | 30 | 36 | 18 | 11  | 170 | 110 ±0.2 | 11   |
| 500-000921 | 30 | 12   | 40   | 25 | 30 | 18 | 11  | 170 | 110 ±0.2 | 11   |
| 500-000922 | 25 | 12.5 | 37.5 | 25 | 26 | 18 | 11  | 160 | 110 ±0.2 | 10.6 |
| 500-000925 | 20 | 12.5 | 37.5 | 25 | 26 | 15 | 9   | 110 | 70 ±0.2  | 9    |
| 500-000930 | 20 | 10   | 27   | 20 | 17 | 15 | 9   | 110 | 70 ±0.2  | 9    |
| 500-000931 | 14 | 10   | 27   | 20 | 17 | 10 | 5.5 | 76  | 48 ±0.2  | 5.7  |
| 500-000932 | 15 | 10   | 27   | 20 | 17 | 15 | 9   | 90  | 60 ±0.2  | 9    |

#### **External Stop Buffer**

The external stop buffer is mounted in the grooves of the HLE/HLEZ profile and can be adjusted infinitely.



| Frame size      | Туре   | В  | D  | d1    | d2   | L   | LA | PA | PL | t   | Part No. (including 2<br>matching socket head<br>screws and t-nuts) |
|-----------------|--------|----|----|-------|------|-----|----|----|----|-----|---|
| LEB100          | EAP100 | 30 | 20 | Ø 6.6 | Ø 11 | 90  | 60 | 40 | 24 | 6.8 | 510-001285  |
| LEB150 / LEZ150 | EAP150 | 30 | 20 | Ø 9   | Ø 15 | 140 | 90 | 90 | 24 | 9   | 510-001385  |

### Longitudinal Flange Set

The working stroke can be more than doubled when using the flange plates. A longitudinal flange is required if the travel path exceeds the profile length (see: technical data, page 16 and 27): The separation of the profiles is made, if possible and not stated otherwise, in the middle. The cut-off point of the longitudinal flanges should always be located near a fixation point. The support distance should be between 1.0 m and 1.5 m For a HLE with toothed belt drive and longitudinal flanges, the load characteristics must be derated (if the maximum travel is exceeded, see technical data, page16) and it should only be used with the profile opening at the top or at the bottom.

|                          | Unit   | LEB100     | LEB150     | LEZ150           |
|--------------------------|--------|------------|------------|------------------|
| maximum permissible load | [N]    | 0.5 x Fx*1 | 0.5 x Fx*1 | unchanged        |
| Speed                    | [m/s]  | < 1        | < 1        | (see on page 27) |
| Acceleration             | [m/s²] | < 1        | < 1        |                  |
| Repeatability            | [mm]   | > ±0.5     | > ±0.5     |                  |

\*1. Fx-HLE: see on page 16



| Frame size      | Туре   | FL  | FB  | FD | HB  |
|-----------------|--------|-----|-----|----|-----|
| LEB100          | LVS100 | 400 | 90  | 15 | 100 |
| LEB150 / LEZ150 | LVS150 | 500 | 130 | 15 | 150 |

### Intermediate Shaft Bearing for HLE Double Axes

The intermediate shaft bearing is used to support the connection shaft of a HLE double axis in the event of a long axis distance. The intermediate shaft bearing must be used if the critical rotational speed (see diagram on the left) is exceeded with the double actuator connection shaft:



Dimensions in [mm] Schematic representation







| Frame size | Туре   | Α    | В  | С    | d   | н  | К  | K1 | М   | W   | Art. No.   |
|------------|--------|------|----|------|-----|----|----|----|-----|-----|------------|
| LEB100     | PASE20 | 33.3 | 32 | 14.5 | Ø20 | 64 | 11 | 8  | 97  | 130 | 416-000120 |
| LEB150     | PASE30 | 42.9 | 40 | 17   | Ø30 | 82 | 14 | 8  | 118 | 158 | 416-000160 |

σ

#### 35

#### Position Switch Attachment / electronic accessories

#### Mounting configurations of the position switch

As a standard, tripping plate, switches and distribution box are mounted on the motor side. The limit switches are fitted ensuring that they are activated directly before the start of the standard safety travel (125 mm). Unless otherwise agreed, the linear actuator is supplied with position sensors attached using attachment variant 1 or 2. The tripping plates, position sensors and distribution box are described on pages 37 et

#### Attachment variant 1: HLE/HLEZ with 3 electrical initiators

This is the standard initiator attachment variant.



seqq.



| Size | Unit | Standard HLE<br>LEB100 LEB150 |     |     | HLE wit | th steel st<br>LEB | HLEZ<br>LEZ150 |     |     |     |     |
|------|------|-------------------------------|-----|-----|---------|--------------------|----------------|-----|-----|-----|-----|
|      |      | S/T                           | E/F | S/T | E/F     | S/T                | E/F            | S/T | E/F | S/T | E/F |
| с    | [mm] | 248                           | 323 | 285 | 360     | 293                | 368            | 330 | 405 | 330 | 405 |
| d    | [mm] | 260                           | 335 | 297 | 372     | 305                | 380            | 342 | 417 | 782 | 857 |

The tripping plate is enclosed separately into the delivery for the carriage configuration with bar (T/F)

#### Mounting configuration 2: HLE with 2 mechanical limit switches and an electrical home sensor





| Size | Unit | Standard HLE<br>LEB100 LEB150 |     |     | HLE wit | th steel st<br>LEB | HLEZ<br>LEZ150 |     |     |     |     |
|------|------|-------------------------------|-----|-----|---------|--------------------|----------------|-----|-----|-----|-----|
|      |      | S/T                           | E/F | S/T | E/F     | S/T                | E/F            | S/T | E/F | S/T | E/F |
| е    | [mm] | 229                           | 304 | 266 | 341     | 274                | 349            | 311 | 386 | 311 | 386 |
| f    | [mm] | 280                           | 355 | 317 | 392     | 325                | 400            | 362 | 437 | 802 | 877 |

The tripping plate is enclosed separately into the delivery for the carriage configuration with bar (T/F)
## Mounting configuration 4: HLE with 1 mechanical limit switche and an electrical home sensor, both moving along

This variant is preferred in robotic systems, if the supply of the switches is made via the cable carrier. The tripping plates must be mounted so that the mechanical switch is actuated immediately before the beginning of the safety travel.



| Size | Unit | Standard HLE<br>LEB100 LEB150 |     |     |     | HLE wit | th steel st<br>LEB | LEB100 | HLEZ<br>LEZ150 |     |     |
|------|------|-------------------------------|-----|-----|-----|---------|--------------------|--------|----------------|-----|-----|
|      |      | S/T                           | E/F | S/T | E/F | S/T     | E/F                | S/T    | E/F            | S/T | E/F |
| g    | [mm] | 295                           | 370 | 332 | 407 | 340     | 415                | 377    | 452            | 377 | 452 |
| h    | [mm] | 312                           | 387 | 349 | 424 | 357     | 432                | 394    | 469            | 825 | 900 |

The initiator and the limit switch are enclosed separately into the delivery for the carriage configuration with bar (T/F).

#### **Tripping plate**

The tripping plate is suitable for all standard load attachment plates. It is fixed to the load attachment plate with the aid of cylinder head screws and square nuts.





Art. No. Tripping plate: 500-000531 Order No. Square nut (2 pcs. required): 135-700001 Art. No. Cylinder head screw M4x6 (2 pcs. required): 130-302294

#### **Mechanical limit switch**

The limit switch corresponds to DIN EN 50047. The contacts satisfy the safety requirements by forced opening in accordance with EN 60947-5-1.



#### **Electrical initiators**

The initiators are activated by a tripping plate on the side on the flange plate.



(Plate, nuts, bolts and washers)

| Technic             | cal data        | Electrical data      |                         |  |  |  |
|---------------------|-----------------|----------------------|-------------------------|--|--|--|
| Switching distance  | 2mm / 4mm ± 10% | Rated Voltage        | 24 V DC                 |  |  |  |
| Switch hysteresis   | > 1%< 15%       | Voltage range        | 1035 V DC               |  |  |  |
| Repeatability       | 0.01 mm         | Supply current       | < 15 mA                 |  |  |  |
| Temperature drift   | < 10 %          | Maximum load current | 300 mA                  |  |  |  |
| Ambient temperature | -25°C - +70°C   | Residual voltage     | < 2.5 V DC              |  |  |  |
| Protection class    | IP67            | Switching frequency  | 2 kHz                   |  |  |  |
| Cable length        | 6 m             | Connecting cables    | 3 x 0.25mm <sup>2</sup> |  |  |  |

| Туре  | Designation  | Part number     |                   |  |
|-------|--|-----------------|-------------------|--|
|       |  | Standard design | Stainless version |  |
| LE100 | Electrical limit switch NPN normally closed contact with 6 m cable and fixing material | 510-900522      | 510-900632        |  |
| LE100 | Electrical limit switch NPN normally open contact with 6 m cable and fixing material   | 510-900520      | 510-900630        |  |
| LE100 | Electrical limit switch PNP normally closed contact with 6 m cable and fixing material | 510-900600      | 510-900631        |  |
| LE100 | Electrical limit switch PNP normally open contact with 6 m cable and fixing material   | 510-900523      | 510-900633        |  |
| LE150 | Electrical limit switch NPN normally closed contact with 6 m cable and fixing material | 510-900527      | 510-900622        |  |
| LE150 | Electrical limit switch NPN normally open contact with 6 m cable and fixing material   | 510-900525      | 510-900620        |  |
| LE150 | Electrical limit switch PNP normally closed contact with 6 m cable and fixing material | 510-900602      | 510-900621        |  |
| LE150 | Electrical limit switch PNP normally open contact with 6 m cable and fixing material   | 510-900528      | 510-900623        |  |

#### **Distribution box**



| Ini end<br>I limit 1<br>E+<br>N.C. | +24V<br>brown<br>Sig. E1<br>black<br>GND<br>blue | )<br> |    | X4/12 |                  | Distribution<br>+24V | box | Controller/<br>controlling |
|------------------------------------|--|-------|----|-------|------------------|----------------------|-----|----------------------------|
|                                    | +24V   | X2/6  |    | X4/15 |                  | Sig. E1              |     |                            |
| Ini Machine                        | brown<br>Sig. MN                                 | X2/5  |    | X4/14 |                  | yellow<br>Sig. MN    |     |                            |
| N.C.                               | black<br>GND                                     | X2/4  |    | X4/13 |                  | green<br>Sig. E2     |     |                            |
|                                    | blue   | Ĭ     | 16 |       | Í                | white                |     | ĺ                          |
|                                    | +24V   | X1/3  |    | X4/10 | $\left  \right $ | <u>GND</u><br>blue   | +   |                            |
| Ini End                            | brown<br>Sig. E2                                 | X1/2  |    |       | V                | Diue                 | ¥.  |                            |
| ı E-<br>N.C.                       | black  | x1/1  |    |       |                  |                      |     |                            |
|                                    | blue   |       |    |       |                  |                      |     | ]                          |

| Designation                             | Part number |
|---|-------------|
| Distribution box including 2.5 m cable  | 800-003102  |
| Distribution box including 5 m cable    | 800-003103  |
| Distribution box including 7.5 m cable  | 800-003104  |
| Distribution box including 10 m cable   | 800-003105  |
| Distribution box including 12.5 m cable | 800-003106  |
| Distribution box including 15 m cable   | 800-003107  |
| Distribution box including 20 m cable   | 800-003108  |
| Distribution box including 25 m cable   | 800-003109  |
| Distribution box including 30 m cable   | 800-003110  |
| Distribution box including 35 m cable   | 800-003111  |
| Distribution box including 40 m cable   | 800-003112  |
| Distribution box including 45 m cable   | 800-003113  |
| Distribution box including 50 m cable   | 800-003114  |

| Frame | Designation   | Art. No.   |                   |  |  |
|-------|---|------------|-------------------|--|--|
| size  | (Art. No. of the distribution boxes: see table above) | Standard   | Stainless version |  |  |
| LB080 | Attachment components for distribution box            | 510-900710 | 510-900712        |  |  |
| LB120 | Attachment components for distribution box            | 510-900612 | 510-900613        |  |  |
| LB180 | Attachment components for distribution box            | 510-900670 | 510-900672        |  |  |



Only for limit switch attachment variant 2

### **Cable Carrier**

A cable carrier is needed when making power connections to moving elements. The cable carrier chain consists of Igumid<sup>®</sup> and the support profile is made of aluminum.



The process for fully determining the dimensions of a cable carrier is very complex. The examples listed below represent simple applications, but more data will normally be required when the situation is less straightforward. The following descriptions are only valid for cable carriers in horizontal configuration supported by a profile - within the limits stated in the technical specifications. If your application is more complicated,

please contact us.

#### Dimensions of supporting profile and carrier chain











|              | Туре  | KR        | Α       | В       | С       | D         | Е         | F          | d         | Art. No. (Length, see chapter: Determination of the chain length) |  |  |
|--------------|---|-----------|---------|---------|---------|-----------|-----------|------------|-----------|---|--|--|
|              |   |           |         |         |         | max.      |           |            | max.      |   | Connection elements fix point and dri-<br>ving plate (inelastic) (please refer to the next page) |  |
|              | B15.015.038.0   | 38        | 15      | 26      | 31      | 120       | 23        | 17.5       | 14        | 100-905150  | 100-905006   |  |
|              | B15.025.038.0   | 38        | 25      | 36      | 41      | 120       | 23        | 17.5       | 14        | 100-905170  | 100-905178   |  |
| with<br>KSP1 | 2500.03.055.0   | 55        | 38      | 54      | 61      | 170       | 35        | 25         | 23        | 100-905810  | 100-905818   |  |
| KS           | 2500.03.100.0   | 100       | 38      | 54      | 61      | 260       | 35        | 25         | 23        | 100-905830  | 100-905838   |  |
|              | 2500.05.100.0   | 100       | 57      | 73      | 78      | 260       | 35        | 25         | 23        | 100-905850  | 100-905858   |  |
|              | 2500.07.150.0   | 150       | 77      | 93      | 98      | 360       | 35        | 25         | 23        | 100-905860  | 100-905868   |  |
| - 0          | 2700.07.200.0   | 200       | 75      | 91      | 96      | 485       | 50        | 35         | 32        | 100-905861  | 100-905869   |  |
| with<br>KSP2 | 2700.12.200.0   | 200       | 125     | 141     | 146     | 485       | 50        | 35         | 32        | 100-905921  | 100-905928   |  |
| ~ ~          | 2700.17.200.0   | 200       | 175     | 194     | 199     | 485       | 50        | 35         | 32        | 100-905960  | 100-905968   |  |
| KSP1 s       | KSP1 small cable supporting profile (Please state required length. Length = stroke) |           |         |         |         |           | = stroke) | 400-010120 |           |   |  |  |
| KSP2 la      | arge cable supporting   | g profile | e (Plea | ise sta | te requ | uired len | gth. L    | .ength     | = stroke) | 400-010121  |  |  |





Dimensional drawings of the connection elements (fixed point and driving plate, both inelastic): see on the next page

| Туре          | Bending<br>radius<br>KR | Pitch | Height         | Curve<br>protrusion | Connection<br>height | Clearance<br>mounting<br>height | Own<br>chain weight |
|---------------|-------------------------|-------|----------------|---------------------|----------------------|---------------------------------|---------------------|
|               |                         | t     | h <sub>g</sub> | Ü <sub>B</sub>      | н                    | H <sub>F</sub>                  | [kg/m]              |
| B15.015.038.0 | 38                      | 30.5  | 23             | 80                  | 100                  | 120                             | ≈ 0.35              |
| B15.025.038.0 | 38                      | 30.5  | 23             | 80                  | 100                  | 120                             | ≈ 0.40              |
| 2500.03.055.0 | 55                      | 46    | 35             | 125                 | 145                  | 170                             | ≈ 0.81              |
| 2500.03.100.0 | 100                     | 46    | 35             | 170                 | 235                  | 260                             | ≈ 0.81              |
| 2500.05.100.0 | 100                     | 46    | 35             | 170                 | 235                  | 260                             | ≈ 0.90              |
| 2500.07.150.0 | 150                     | 46    | 35             | 220                 | 335                  | 360                             | ≈ 1.01              |
| 2700.07.200.0 | 200                     | 56    | 50             | 275                 | 450                  | 485                             | ≈ 1.30              |
| 2700.12.200.0 | 200                     | 56    | 50             | 275                 | 450                  | 485                             | ≈ 1.48              |
| 2700.17.200.0 | 200                     | 56    | 50             | 275                 | 450                  | 485                             | ≈ 1.85              |

#### Dimensional drawings of the connection points

for type B15.xxx

#### for type 2500.xxx

for type 2700.xxx













| Туре    | Α  | В    |
|---------|----|------|
| B15.015 | 0  | 25.5 |
| B15.025 | 10 | 35.5 |
|         |    |      |

| Type    | ~  | U U |
|---------|----|-----|
| 2500.03 | 25 | 51  |
| 2500.05 | 44 | 70  |
| 2500.07 | 64 | 90  |

| Туре    | Α   | В   |
|---------|-----|-----|
| 2700.07 | 55  | 93  |
| 2700.12 | 105 | 143 |
| 2700.17 | 155 | 196 |

#### **Technical data**

| for type | Car                    | ntilever configurat    | tion   | Cantilever configuration with permitted sag |                        |                                |  |  |
|----------|------------------------|------------------------|--|---|------------------------|--------------------------------|--|--|
|          | max.<br>travel<br>[mm] | max.<br>speed<br>[m/s] | max.<br>acceleration <sup>1</sup><br>[m/s <sup>2</sup> ] | max.<br>travel <sup>2</sup><br>[mm]         | max.<br>speed<br>[m/s] | max.<br>acceleration<br>[m/s²] |  |  |
| B15.xx   | 2000                   | 10                     | 20   | 2400  | 3                      | 6                              |  |  |
| 2500.xx  | 2300                   | 10                     | 20   | 4000  | 3                      | 6                              |  |  |
| 2700.xx  | 3000                   | 10                     | 20   | 4300  | 3                      | 6                              |  |  |

Higher speeds or accelerations will reduce the lifetime of the cable carrier.

Usual lifetime range with cantilever configuration: 5 - 10 Million strokes. For longer strokes, a sliding chain configuration is used. Please contact the supplier.

#### **Guidelines for using cable carriers**



Use only electrical cables suitable for use in cable carriers. Hose lines should be highly flexible and should only extend or shorten slightly under pressure. Weight should be distributed across the cable track as evenly as possible! Cables must not be twisted when routed in the cable carrier and should be routed next to one another and as loosely as possible.



Avoid laying several lines on top of each other and laying lines of different diameters directly next to one another. If multiple layers must be used, separating strips should be inserted between each layer - should such circumstances arise, please contact Parker.

If there is no alternative to routing several lines beside each other without sub-divisions, the clearance height within the carrier must be less than the line diameter. This is the only way of preventing the cables from twisting.



The supply cables must be free to move within the cable carrier. They cannot be fixed to the cable carrier or tied together. **Separating strips** must always be inserted between flat cables routed in multiple layers.

#### **Recommended dimensions of the space required:**

| for round cables: | approx. 10 % of the line diameter                   |
|-------------------|---|
| with flat cables: | for each, approx. 10 % of the cable width and cable |
| thickness         |   |
| with hose lines:  | approx. 20 % of the hose diameter                   |

Thin highflex cables with a low bending strength must be bundled and inserted into a protective hose. The cross section of the protective hose must be much larger than the sum of the individual cable cross sections. For the calculation of the cross section you should assume a standard clearance of 10 % of the individual line diameter.

#### Load diagrams

Self-supporting length depending on the additional load



Length with permitted sag LD and travels



#### Determination of the chain length

## $L\kappa = \frac{S}{2} + K$

|                   |     |     | Round LK to |     |     |         |
|-------------------|-----|-----|-------------|-----|-----|---------|
| Bending radius KR | 38  | 55  | 100         | 150 | 200 | pitch t |
| B15.xx            | 185 |     |             |     |     | 30.5    |
| 2500.xx           |     | 276 | 414         | 578 |     | 46      |
| 2700.xx           |     |     |             |     | 825 | 56      |

### Additional Accessories / Software

#### Belt tension measuring device RSM:

For accurately setting the toothed belt tension. (Art. No.: 037-000201)



#### DimAxes:

Dimensioning software for EME linear modules HPLA, HLE, HZR, HTR, BLMA - for PCs as from Windows version 95





Free download of the DimAxes Software or CAD files, catalogs and manuals, partly in different languages on: http://www.parker-eme.com/hle

# **HLE Order Code**

|   | LE   |  |                              |                     |                          |   | P   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
|---|--|--|------------------------------|---------------------|--------------------------|---|---|--|--|--|--|---|---|--------------------------------------|---|--------|--------|---|--------|----|----|
| Drive system  |  |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Toothed belt drive  |  | в  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| dler unit   |  | Ν  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Frame size  |  |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| 100 (Dimensional drawing page   | 18)  |  | 1                            | 0                   | 0                        |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| 150 (Dimensional drawing page 2   |  |  | 1                            | 5                   | 0                        |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Carriage  |  |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Standard carriage with load attac   | chment plat  | te   |                              |                     |                          | s   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Standard carriage with bar  | , and the second s |  |                              |                     |                          | Т   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Extended carriage with load atta  | chment pla   | ite  |                              |                     |                          | E   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Extended carriage with bar  |  |  |                              |                     |                          | F   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Special carriage with load attach   | ment plate   | (on  | requ                         | est)                |                          | C   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Special carriage with bar (on requ  | -  | (0111  | oqu                          | 001)                |                          | D   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Extra (e.g. two or more carriages   |  | st)  |                              |                     |                          | X   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Guide system  | , on requee  | ,  |                              |                     |                          | ~   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Plastic coated rollers  |  |  |                              |                     |                          |   | Р   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| Stroke  |  |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
| State desired stroke [mm]   |  |  |                              |                     |                          |   |   | n  | n  | n n  | n                                      |   |   |                                      |   |        |        |   |        |    |    |
| Drive options (see figures below  | d)   |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
|   |  | . aeo  | 10 0                         | 21)                 |                          |   |   |  |  |  |  | s |   |                                      |   |        |        |   |        |    |    |
| Shaft on left (Dimensional drawin   |  | -  |                              |                     |                          |   |   |  |  |  |  | S | L |                                      |   |        |        |   |        |    |    |
| Shaft on right (Dimensional draw  |  | -  |                              |                     | 0.01)                    |   |   |  |  |  |  | S | R |                                      |   |        |        |   |        |    |    |
| Shaft on both sides (Dimensional  |  |  |                              |                     |                          |   | e   |  |  | 41.  | . 1.4                                  |   | В |                                      |   |        |        |   |        |    |    |
| Toothed pulley separately included for  | •  |  |                              |                     |                          | •   |   |  |  | •  |  | N | L |                                      |   |        |        |   |        |    |    |
| Toothed pulley separately included for  | , v  |  |                              |                     |                          |   |   |  | Ű  |  | · ·                                    | N | R |                                      |   |        |        |   |        |    |    |
| Gearbox on the left, additional sh  |  | -  |                              |                     |                          |   |   |  | -  |  | -                                      | L | R |                                      |   |        |        |   |        |    |    |
| Gearbox on the right, additional s  |  |  |                              |                     |                          | drawi   | ngs:  | see p  | bages  | 19, 2  | 1)                                     | R | L |                                      |   |        |        |   |        |    |    |
|   |  |  |                              |                     |                          |   |   |  |  |  |  |   |   |                                      |   |        |        |   |        |    |    |
|   |  |  |                              |                     |                          |   |   |  |  |  |  | N | N |                                      |   |        |        |   |        |    |    |
|   |  |  |                              |                     |                          |   |   |  |  |  |  | X | X |                                      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f   |  |  |                              |                     |                          |   |   |  | e  |  | ngth                                   |   |   |                                      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f   |  |  |                              |                     |                          | 100   | 150   | t H7   | circle   | aft<br>H7                                    | t length                               |   |   |                                      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f   |  |  |                              |                     |                          | FR100   | FB150                                       | Pilot H7                                       | 3olt circle  | 0Shaft<br>bore H7                            | Shaft length                           |   |   |                                      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for  | or double a  |  |                              |                     |                          | X<br>FR100  |   | 05<br>Pilot H7                                 |  | 0 ØShaft<br>bore H7                          | 6 Shaft length                         |   |   | к                                    |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60  | or double a  |  |                              |                     |                          |   |   | 50   | 70   | 16   |  |   |   | K                                    |   |        |        |   |        |    |    |
| Without drive – idler unit (Dimens<br>Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11  | or double a  |  |                              |                     |                          | х   | x   | 50<br>80                                       | 70<br>100  | 16<br>22                                     | 40<br>52                               |   |   | М                                    |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11  | or double a  |  |                              |                     |                          | ×   | x<br>x                                      | 50<br>80<br>110                                | 70<br>100<br>130   | 16<br>22<br>32                               | 40<br>52<br>68                         |   |   | M<br>P                               |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3   | or double a  | axes)  |                              |                     |                          | x   | X<br>X                                      | 50<br>80<br>110<br>60                          | 70<br>100<br>130<br>75   | 16<br>22<br>32<br>16                         | 40<br>52<br>68<br>48                   |   |   | M<br>P<br>A                          |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet  | or double a  | x P4   |                              |                     |                          | x   |   | 50<br>80<br>110<br>60<br>70                    | 70<br>100<br>130<br>75<br>85   | 16<br>22<br>32<br>16<br>22                   | 40<br>52<br>68<br>48<br>56             |   |   | M<br>P<br>A<br>B                     |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet   | or double a<br>5<br>ary gearbo<br>ary gearbo   | x P4<br>x P5                                   | (on                          | requ                |                          |   |   | 50<br>80<br>110<br>60<br>70<br>90              | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> </ul>              | 16<br>22<br>32<br>16<br>22<br>32             | 40<br>52<br>68<br>48<br>56<br>88       |   |   | M<br>P<br>A<br>B<br>C                |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea  | or double a<br>5<br>ary gearbo<br>ary gearbo<br>rbox PL4-C   | x P4<br>x P5<br>DP11                           | (on                          | PE4                 |                          |   |   | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q           |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea   | or double a<br>5<br>ary gearbo<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C   | x P4<br>x P5<br>DP11<br>DP11                   | or F<br>or F                 | PE4<br>PE5          | est))                    |   |   | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> </ul>              | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88       |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler  | or double a<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an   | x P4<br>x P5<br>DP11<br>DP11                   | or F<br>or F                 | PE4<br>PE5          | est))                    |   |   | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re   | or double a<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)  | x P4<br>x P5<br>DP11<br>DP11<br>d dri          | or F<br>or F<br>ve o         | PE4<br>PE5<br>ptior | est))<br>ss SL           | x<br>x<br>x<br>x<br>x<br>x<br>x<br>, SR, S  | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R      |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe   | or double a<br>5<br>ary gearbo<br>rbox PL4-0<br>rbox PL5-0<br>unit NN an<br>equest)<br>is (from ax   | x P4<br>x P5<br>DP11<br>DP11<br>d dri          | or F<br>or F<br>ve o         | PE4<br>PE5<br>ptior | est))<br>ss SL           | x<br>x<br>x<br>x<br>x<br>x<br>x<br>, SR, S  | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br><b>Center distance for double axe</b><br>Specify required center distance  | or double a<br>5<br>ary gearbo<br>rbox PL4-0<br>rbox PL5-0<br>unit NN an<br>equest)<br>is (from ax   | x P4<br>x P5<br>DP11<br>DP11<br>d dri          | or F<br>or F<br>ve o         | PE4<br>PE5<br>ptior | est))<br>ss SL           | x<br>x<br>x<br>x<br>x<br>x<br>x<br>, SR, S  | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N | n | n      | n      | n | n      |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br><b>Center distance for double axe</b><br>Specify required center distance<br>State for single axis or idler unit   | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>ss (from ax<br>(in mm)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri          | or F<br>or F<br>ve o         | PE4<br>PE5<br>ptior | est))<br>ss SL           | x<br>x<br>x<br>x<br>x<br>x<br>x<br>, SR, S  | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N | n | n<br>0 | n<br>0 | n | n<br>0 |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br><b>Center distance for double axe</b><br>Specify required center distance<br>State for single axis or idler unit<br><b>Steel strip cover</b> (see on page 1  | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>ss (from ax<br>(in mm)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri          | or F<br>or F<br>ve o         | PE4<br>PE5<br>ptior | est))<br>ss SL           | x<br>x<br>x<br>x<br>x<br>x<br>x<br>, SR, S  | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80        | <ul> <li>70</li> <li>100</li> <li>130</li> <li>75</li> <li>85</li> <li>120</li> <li>100</li> </ul> | 16<br>22<br>32<br>16<br>22<br>32<br>32<br>20 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover  | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        | Ν  |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover<br>With steel strip cover (protection                                | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        | NC |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover<br>With steel strip cover (protection<br>Material version   | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover<br>With steel strip cover (protection<br>Material version<br>Standard versions                            | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    | Ν  |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover<br>With steel strip cover (protection<br>Material version<br>Standard versions                            | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    | NV |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler  | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |
| Extras (others, e.g. center drive f<br>Drive flange suitable for<br>Bayside planetary gearbox PS60<br>Bayside planetary gearbox PS90<br>Bayside planetary gearbox PS11<br>Stöber planetary gearbox P3<br>Flange suitable for Stöber planet<br>Flange suitable for Stöber planet<br>Flange suitable for planetary gea<br>Without gearbox flange (for idler<br>Extra (others, non standard, on re<br>Center distance for double axe<br>Specify required center distance<br>State for single axis or idler unit<br>Steel strip cover (see on page 1<br>Without steel strip cover<br>With steel strip cover (protection<br>Material version<br>Standard versions<br>Stainless version (V2A) | or double a<br>5<br>5<br>ary gearbo<br>rbox PL4-C<br>rbox PL5-C<br>unit NN an<br>equest)<br>es (from ax<br>(in mm)<br>4)<br>class IP30   | x P4<br>x P5<br>DP11<br>DP11<br>d dri<br>is ce | or F<br>or F<br>or F<br>ve o | PE4<br>PE5<br>ptior | est))<br>as SL<br>axis o | x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x<br>x | : x<br>x<br>: x<br>: x<br>: x<br>: x<br>SB) | 50<br>80<br>110<br>60<br>70<br>90<br>80<br>110 | 70<br>100<br>130<br>75<br>85<br>120<br>100<br>130  | 16<br>22<br>32<br>16<br>22<br>32<br>20<br>25 | 40<br>52<br>68<br>48<br>56<br>88<br>40 |   |   | M<br>P<br>A<br>B<br>C<br>Q<br>R<br>N |   |        |        |   |        |    |    |



NR

LR

RL

NN

# HLEZ150 Order Code

| HLEZ linear module                                   |        |        |       |        | Р   |   |   |   |   |   |   |   |   |   |   |   |   |   | N | N | N |
|--|--------|--------|-------|--------|-----|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Drive system   |        |        |       | _      |     |   |   |   |   |   |   |   |   |   |   |   |   |   | _ |   |   |
| Toothed belt drive Z                                 |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Frame size   |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| 150 (Dimensional drawing on page 29)                 | 1      | 5      | 0     |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Carriage   |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Standard carriage with load attachment plate         |        |        |       | S      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Standard carriage with bar                           |        |        |       | Т      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Extended carriage with load attachment plate         |        |        |       | Е      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Extended carriage with bar                           |        |        |       | F      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Special carriage with load attachment plate (on      | requ   | est)   |       | С      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Special carriage with bar (on request)               |        |        |       | D      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Extra (e.g. two or more carriages, on request)       |        |        |       | Х      |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Guide system   |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Plastic coated rollers                               |        |        |       |        | Р   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Stroke   |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| State desired stroke [mm]                            |        |        |       |        |     | n | n | n | n | n |   |   |   |   |   |   |   |   |   |   |   |
| Drive options (Definition for right/left: see figure | e belo | ow)    |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Shaft on left  |        |        |       |        |     |   |   |   |   |   | S | L |   |   |   |   |   |   |   |   |   |
| Shaft on right                                       |        |        |       |        |     |   |   |   |   |   | S | R |   |   |   |   |   |   |   |   |   |
| Gearbox on left                                      |        |        |       |        |     |   |   |   |   |   | D | L |   |   |   |   |   |   |   |   |   |
| Gearbox on right                                     |        |        |       |        |     |   |   |   |   |   | D | R |   |   |   |   |   |   |   |   |   |
| Extras (other drive versions)                        |        |        |       |        |     |   |   |   |   |   | Х | Х |   |   |   |   |   |   |   |   |   |
| Gearbox flange                                       |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Flange suitable for worm gearbox                     |        |        |       |        |     |   |   |   |   |   |   |   | L |   |   |   |   |   |   |   |   |
| Flange suitable for planetary gearbox PL5 OP1        | l or P | °E5    |       |        |     |   |   |   |   |   |   |   | R |   |   |   |   |   |   |   |   |
| Without gearbox flange - with drive options SL,      | SR     |        |       |        |     |   |   |   |   |   |   |   | Ν |   |   |   |   |   |   |   |   |
| Extra (others, non standard, on request)             |        |        |       |        |     |   |   |   |   |   |   |   | Х |   |   |   |   |   |   |   |   |
| Center distance for double axes (from axis ce        | nter t | to axi | is ce | enter) |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| State for single axis or idler unit [mm]             |        |        |       |        |     |   |   |   |   |   |   |   |   | 0 | 0 | 0 | 0 | 0 |   |   |   |
| State desired center distance [mm] - non stand       | ard -  | only   | on r  | eques  | st! |   |   |   |   |   |   |   |   | n | n | n | n | n |   |   |   |
| Steel strip cover                                    |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Without steel strip cover (standard)                 |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   | Ν |   |   |
| Material version                                     |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Standard versions                                    |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   | Ν |   |
| Linear encoder                                       |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   |
| Without linear encoder (standard)                    |        |        |       |        |     |   |   |   |   |   |   |   |   |   |   |   |   |   |   |   | Ν |

Characteristics right / left: Looking from load attachment plate to drive module.



Additional information available on:

www.parker-eme.com/hle



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