





# **Quick installation guide**



MI HI 02 08/07 E August 2007 (software rel. 10)



### SAFETY INSTRUCTIONS



### **General information**

Only persons who are qualified and trained for the use and operation of the equipment may work on this equipment or within its proximity. The persons are qualified if they have sufficient knowledge of the assembly, transportation, installation and operation of the equipment as well as an understanding of all warnings and precautionary measures noted in these instructions. The user must also observe local safety regulations. Before installing and commissioning the drive, read carefully this documentation and strictly observe all technical, safety and wiring information, including identifying labels placed on the drive (ratings). In case of doubt contact the Parker Hannifin service centre. Drives are to be intended as components for use in machine or systems. Therefore they can be used only in machine or systems that are in compliance with the low voltage directive 73/23/CEE (modified by 93/68/CEE) and with the electro-magnetic compatibility directive 89/336/CEE. Electronic equipments are generally not "fail-safe" components. Therefore the machine manufacturers should carry out a risk analysis for the whole machine in order to ensure that moving parts (motors) cannot bring personal injury in case of failures of electronic devices.

### Safety instructions for transportation and storage

The ambient conditions given in the product documentation must be observed for transportation and storage (temperature, humidity, mechanical stress and aggressive atmosphere). Drives contain components sensitive to electrostatic charges which can be damaged by inappropriate handling. Therefore during installation / removal of drives, provide the necessary safety precautions against electrostatic discharges (discharge electrostatic charges of the human body before touching the drive, always place the drive above conductive plates and avoid touching it with insulating material like synthetic fibres, polymeric materials etc...)

**Risk of injury by incorrect handling !** Incorrect handing of the equipment may cause severe personal injury. Use appropriate tools for transportation, lifting, handling and mounting. Wear appropriate clothing for accident-prevention (safety shoes, safety glasses, safety gloves, etc...). Safety instructions for commissioning

The high voltages inside the drive imply risk of electric shock. Make sure that drive and motor are properly grounded accordingly to national regulations. Furthermore the drive, before switching it on, must be closed in a protective cabinet in order to avoid direct contact with accessible live parts. Only qualified and trained personnel is allowed to perform installation and commissioning, using appropriate tools and following the safety precautions given in this instruction. Make sure that supply voltage has been switched off before installing and wiring. Drives are only allowed to be operated on TT, TN grounded industrial mains having maximum 480V+10% line to line rms voltage, as specified in the user manual. Do not directly install the drive on ungrounded (IT) or asymmetrically grounded mains. In case of ungrounded mains, coupling with Dyn transformer with grounded secondary circuit is necessary. Refer to drive technical data and wiring instruction. All the components used in the cabinet in which the drive is installed, (cables, contactors, inductors and transformers, fuses, etc...), and the connected motor, must be in compliance with the specification given in the instruction. The size and temperature rating of wires and cables used for connecting the drive must be in compliance with the specification given in the instruction manual (see NEC 310-16 for USA). Use also the specified tightening torque. Make sure

about the correct drive-motor matching: voltage and current ratings must be compatible. The user is responsible for over-current and short circuit protection of the drive. Read carefully the specification given in the user manual.

### Safety instructions for operation

**High voltage ! Risk of electric shock ! Danger of life !** All live parts must be protected against direct contact. The drive must be closed inside a cabinet before switching it on. Working on power live parts (terminals) must be conducted with the drive switched-off. Dangerous voltages may be present at power terminals even after the supply has been switched off and the motor stopped. Make sure the equipment cannot switched on unintentionally. Wait at least 6 minutes before working on live parts after the unit has been switched-off. The drive and the motor must be permanently connected to earth accordingly to the connection diagram, even for brief measurements or tests.

High leakage current ! Risk of electric shock ! Danger of life ! Earth leakage current during operation may exceed 3,5 mA AC or 10mA DC. Earth connection must be permanent : use copper wire having a minimum size of 10mm<sup>2</sup> throughout all the length. Before switching the equipment on, make sure that all devices, including the motor, are permanently connected to earth, even for brief test or measurements, as shown in the wiring diagrams. Otherwise high voltages may appear on equipment conductive surfaces with danger of electrical shock. Always refer to current local regulations for grounding. For installation within European Community refer to EN61800-5-1 product standard, section 4.2.5.4.2. For installation in the USA refer to NEC (National Electric Code) and NEMA (National Electric Manufacturers Association). The product installation should always comply with the above said standards.

Hot surfaces ! Danger of injury ! Danger of burns ! Some external surfaces of the equipment and same internal part may reach very high temperatures. Danger of burn and injury if touching these parts.

### After switching the equipment, wait at least 15 minutes to allow it to cool before touching it.

Dangerous movements ! Danger of life !

In order to prevent personal injury due to unintended dangerous motor movements, pay the maximum attention and work on the machine with a qualified and tested safety system.

### Compatibility with RCD devices

The use of RCD (Residual Current Devices) is strongly not recommended. If the use of RCD is mandatory, use type B only (for DC and AC prospective earth current). Set the trip level at 300mA (fire protection level) or more. Setting the trip level at 30mA (protection level against direct contact) is possible only using time-delayed RCD and low leakage current EMC filters, but in any case the drives are not guaranteed to operate with 30mA trip level.

		Applicable standards: Safety		
73/23/CEE directive mod.	by 93/68/CEE	Low voltage directive		
EN 50178		Electronic equipment for use in power installations		
EN 60204-1		Safety of machinery - Electrical equipment of machines - Part 1: General requirements		
EN 61800-2		ljustable speed electrical power drive systems – Part 2: General requirements – Rating specifications fo		
		voltage adjustable frequency a.c. power drive systems		
EN 61800-5-1		Adjustable speed electrical power drive systems – safety requirements, thermal and energy		
UL508C		(USA) Power Conversion Equipment		
CSA22.2 Nr. 14-05		(Canada) Power Conversion Equipment		
	Applica	ble standards: Electromagnetic Compatibility (Immunity/Emission)		
89/336/CEE directive	EMC directive			

EN 61800-3 Adjustable speed electrical power drive systems. Part 3 : EMC product standard including specific test method The drives are to be intended as components to be used in a second environment (industrial environment) and category C3, together with specific EMC filters and installed accordingly to the recommendation given in the user manual. When used in the first environment (residential / commercial environment), drives may produce radio-frequency interference dangerous for other equipments : additional filtering measures must be implemented by the user.

### Materials and disposal

Electrolytic capacitor contain electrolyte and printed circuit boards contain lead, both of which are classified as hazardous waste and must be removed and handled according to local regulations. The S.B.C. division of the Parker Hannifin Company, together with local distributors and in accordance with EU standard 2002/96/EC, undertakes to withdraw and dispose of its products, fully respecting environmental considerations.



This symbol is an invitation to refer to the more detailed information in the integral version of the operator's manual attached to the supply or which can be downloaded from <u>www.sbcelettronica.com</u>

# **1 HARDWARE SPECIFICATIONS**

	Unit	HID2	HID5	HID8	HID10	HID16	HID25	HID35	HID45	HID75	HID100	HID130
Rated output current	Arms	2	5	8	10	16	25	35	45	75	100	130
Peak output current (2 sec)	Arms	4	10	16	20	32	50	70	90	135 (3sec)	180 (3sec)	234 (3sec)
Continuous service installed load	kVA	1,4	3,5	5,6	6,9	11,2	17,5	22,8	28,5	53	70	91
Power stage dissipation	W	30	75	120	140	220	350	490	540	890	1050	1300
Switching frequency (selectable)	kHz	8-16	8-16	-	-		-		-		-	
Default switching frequency	kHz	8	8	8	4	8	3	2	ł		4	
Current derating with $f_{sw} > f_{default}$	p.u.	0	,7		-		-				-	
Current derating with V <sub>main</sub> >440V~	p.u.		C	),9		0	,9				0,9	
Output frequency	Hz		0 -	500		0 -	500	0 -	500		0 - 400	
Internal fan capacity	m <sup>3</sup> /h	32	47	63	63	16	58	26	50	272	459	459
Braking resistor	ohm	200	90	75	75	40	27	1	3	13 (min)	10 (min)	10 (min)
Continuous internal braking power	W	75	75	120	120	180	180	40		20k (max)	25k (max)	25k (max)
Braking power peak 790Vdc	W sec	3120 1	6935 0,7	8320 0,5	8320 0,5	15600 0,2	23115 0,15	480	)00 _1	48000	62400	62400
DC circuit capacity (±20%)	μF	195	390	390	390	585		18	00	3150	5000	5000
Continuous power	W				See o	liagrams					-	
Continuous power @400V~	kW					-			41	55	72	
Braking threshold	Vdc		795 – 770 (-0V +20V)					790 - 770				
Overvoltage level	Vdc		870								870	
Undervoltage level	Vdc				70% *	$\sqrt{2 * V_{max}}$	ins			400 - 440		
EMC filter	-		inte	ernal		exte	rnal	exte	rnal	internal		
Fan supply voltage	V~			-			-			- 230 ±10% (1ph, 50/60 Hz)		
Fan power	W			-					-	-		40

# 2 INSTALLATION

# 2.1 Identification

HID	Servodrive se	eries							
Х	ATEX type of	ATEX type drive							
2	Drive size (n	ominal current, up to 3 digits: 2, 5,	8, 10, 16, 25, 35, 45, 75, 100, 130)						
S	SBC CAN pi	rotocol (standard)							
D	CANopen pr	rotocol (DS402)							
S	Second enco	der input for SinCos signals – 1 V <sub>pp</sub>							
Е		der input for quadrature digital sign							
Н	Second enco	der input for quadrature digital sign	als + Hall sensor signals						
Y1	Slot N. 1	<u>Code optional boards:</u> P = profibus DP - P I = I/O  8DI+8DO - I	S = Sercos D = Devicenet (n.a.) C1 = Robox board up to 1.5 axis (with CANopen DS402) [in 3 Slot]						
Y2	Slot N. 2	E1 = Powerlink (n.a.) E2 = Sercos 3 (n.a.)	C2 = Robox board up to 4 axis (with CANopen DS402) [su 3 Slot] C3 = Robox board up to 32 axis (with CANopen DS402) [su 3 Slot]						
¥3	Slot N. 3	E3 = CIP (n.a.) E4 = Profinet (n.a.) E5 = Ethercat (n.a.)	C4 = Robox board up to TBD (with CANopen DS402) (n.a.) [in 3 Slot] C5 = Robox board up to TBD (with CANopen DS402) (n.a.) [in 3 Slot] C6 = Robox board up to TBD (with CANopen DS402) (n.a.) [in 3 Slot]						
R	Internal safety relay								
М	Memory area for ritentive variables								



Fit a suitable ventilation filter inside the switchboard.

### 2.3 Dimensioni

**IMPORTANT** 



<b>A</b> 87mm 122mm 227mm		HID2 HID5 HID8	HID16 HID25	HID35 HID45
	Α	87mm	122mm	227mm
<b>mass</b> 5,8kg 8,5kg 16kg	mass	5,8kg	8,5kg	16kg

	HID75	HID100	HID130
Y	320mm	365mm	365mm
Ζ	660mm	720mm	720mm
mass	40 kg	59 kg	59 kg



# **3 WIRING CONNECTIONS**

# 3.1 Protection devices

The drive has no protections against short circuits and overload on the mains side.

The user is responsible for	short c	circuit a	and ove	erload th	e protec	tion as f	ollows :				
Model	HID2	HID5	HID8	HID10	HID16	HID25	HID35	HID45	HID75	HID100	HID130
Fuse size on AC power supply network (delayed)	6A	10A	16A	16A	20A	50A	50A	75A	110A	175A	200A
Fuse size on VDC control		3.15A fast									

power supply	5.15A last
A thermo-magnetic switch can l	be used instead of fuses with the same effectiveness, but not in installations with UL standard. For UL
compliant installations, use ultra-	fast fuses accordingly to UL standard (RC, JFHR2).
See the following table:	

Model	HID2	HID5	HID8-HID10	HID16	HID25
Mains AC (3)	Bussmann FWP10A14F Ferraz-Shawmut A70P10-1	Bussmann FWP20A14F Ferraz-Shawmut A70P20-1	Bussmann FWP30A14F Ferraz-Shawmut A70P30-1	Bussmann FWP-50B Ferraz-Shawmut A70P50-4	Bussmann FWP-60B Ferraz-Shawmut A70P60-4
Brake resistor (2)	Bussmann FWP10A14F Ferraz-Shawmut A70P10-1	Bussmann FWP20A14F Ferraz-Shawmut A70P20-1	Bussmann FWP20A14F Ferraz-Shawmut A70P30-1	Bussmann FWP30A14F Ferraz-Shawmut A70P30-1	Bussmann FWP-35B Ferraz-Shawmut A70P35-1
DC Bus (2)	Bussmann FWP10A14F Ferraz-Shawmut A70P10-1	Bussmann FWP20A14F Ferraz-Shawmut A70P20-1	Bussmann FWP30A14F Ferraz-Shawmut A70P30-1	Bussmann FWP-50B Ferraz-Shawmut A70P50-4	Bussmann FWP-60B Ferraz-Shawmut A70P60-4
Model	HID35	HID45	HID75	HID100	HID130
Mains AC (3)	Bussmann FWP-80B Ferraz-Shawmut A70P80-4	Bussmann FWP-100B Ferraz-Shawmut A70P100-4	Bussmann FWP125A Ferraz-Shawmut A70P125-4	Bussmann FWP200A Ferraz-Shawmut A70P200-4	Bussmann FWP225A Ferraz-Shawmut A70P225-4
Brake resistor (2)	Bussmann FWP-80B Ferraz-Shawmut A70P80-4	Bussmann FWP-80B Ferraz-Shawmut A70P80-1	Bussmann FWP-80B Ferraz-Shawmut A70P80-4	Bussmann FWP-100B Ferraz-Shawmut A70P100-4	Bussmann FWP-100B Ferraz-Shawmut A70P100-4
DC Bus (2)	Bussmann FWP-80B Ferraz-Shawmut A70P80-4	Bussmann FWP-100B Ferraz-Shawmut A70P100-4	BussmannFWP175 Ferraz-Shawmut A70P175-4	Bussmann FWP250 Ferraz-Shawmut A70P250-4	Bussmann FWP300 Ferraz-Shawmut A70P300-4

# 3.2 Wiring harness

Il tipo di cavo per posa mobile o fissa deve essere scelto in base all'applicazione. Per la sezione del cavo vedere la tabella seguente:

Model		HID2	HID5	HID8	HID10	HID16	HID25	
MOTOR	Section	1.5mm <sup>2</sup>	1.5mm <sup>2</sup>	2.5mm <sup>2</sup>	2.5mm <sup>2</sup>	4mm <sup>2</sup>	6mm <sup>2</sup>	
	Section	(AWG14)	(AWG14)	(AWG12)	(AWG12)	(AWG8)	(AWG8)	
(X2)	Tightening torque		0.5 - 0.6 N	m (M3)		1.2 Nr	n (M4)	
NETWORK	Section	1.5mm <sup>2</sup>	2.5mm <sup>2</sup>	2.5mm <sup>2</sup>	2.5mm <sup>2</sup>	4mm <sup>2</sup>	6mm <sup>2</sup>	
(X1)	Section	(AWG14)	(AWG12)	(AWG12)	(AWG12)	(AWG8)	(AWG8)	
(A1)	Tightening torque	0.5 - 0.6  Nm (M3)			1.2 Nr	1.2 Nm (M4)		
Signal	Section			0.22 ÷ 1 mm	<sup>2</sup> (AWG16)			
(X5)	Tightening torque			0.22 - 0.25	Nm (M2)			
Stationary harden (V2)	Section	1 mm <sup>2</sup> (AWG16)						
Stationary brake (X3)	Tightening torque	0.5 - 0.6 Nm (M3)						
Max. motor cable length	60 m							
Max cable capacity		< 150 pF/m						

Model		HID35	HID45	HID75	HID100	HID130	
	Section	10mm <sup>2</sup>	10mm <sup>2</sup>	25÷50mm <sup>2</sup>	35÷95mm <sup>2</sup>	35÷95mm <sup>2</sup>	
MOTOR	Section	(AWG6)	(AWG6)	(AWG3-4)	(AWG1)	(AWG2/0)	
	Tightening torque	2.5 Nm	n (M5)	6 ÷ 8 Nm	15 ÷	20 Nm	
	Section	10mm <sup>2</sup>	10mm <sup>2</sup>	25÷50mm <sup>2</sup>	35÷95mm <sup>2</sup>	35÷95mm <sup>2</sup>	
NETWORK	Section	(AWG6)	(AWG6)	(AWG4)	(AWG1)	(AWG2/0)	
	Tightening torque	2.5 Nn	n (M5)	6 ÷ 8 Nm	15 ÷	20 Nm	
External braking	Section	10÷25mm <sup>2</sup> (AV	WG6AWG4)	25÷50mm <sup>2</sup> (AWG8)	6÷8mm <sup>2</sup> (AWG8)	6÷8mm <sup>2</sup> (AWG8)	
resistor	Tightening torque	2.5 Nm	n (M5)	$6 \div 8 \text{ Nm}$	0.7 Nm		
Signal	Section	0.22 ÷ 1 mm	<sup>2</sup> (AWG16)	$0.22 \div 1 \text{ mm}^2$ (AWG16)			
(X5)	Tightening torque	0.22 - 0.25	5 Nm (M2)	0.22 - 0.25 Nm (M2)			
Stationary brake	Section			1mm <sup>2</sup> (AWG16)			
(X3)	Tightening torque	ning torque		0.22 – 0.25 Nm (M2)			
Ean gunnly	Section	-	-	-	2,5mm <sup>2</sup>	(AWG12)	
Fan supply	Tightening torque	-	-	-	0.7 Nm		
Max. motor cable length		60 m 50 m / 300 m with inductance					
Max cable capacity		< 150 pF/m					

All signal cables must have a minimum section of  $0.22 \text{ mm}^2$ . The cables used for analog signals must be shielded twisted pairs. The resolver cable must consist of 4 individually shielded twisted pairs protected by a shield. The conductor-conductor capacity for the length used cannot exceed 10 nF and the section cannot be less than  $0.22 \text{ mm}^2$ . The maximum length is 60 m. The motor cable must be shielded. Shielded cables are also recommended for digital inputs and outputs.

For <u>UL compliant installations</u>, use only stranded copper wire rated for 75°C. Use only appropriate crimping tools to fix terminal lugs. The conductors ampacity shall be 125% of the rated current accordingly to NEC 310-16.

### 3.3 **Connector layout** HID2-...-HID25 HID35-HID45 Upper panel X1 66666666 X1 X3 -X2 T KCI S.B.C. Hi drive X4 X5 Lower panel X6 X7 X8 X9 X10<sup>X11</sup> X6 e . e Front panel HID35-HID45 HID2-...-HID25 Terminal block X1 X 1 Х DC+ 1 1 DC + Ð RP 2 2 RP ❶ RN 3 Φ 3 RN MAINS IN 0 4 IN 4 ٩ 5 BRO BRC 5 • 6 L 1 L 1 6 0 7 L 2 8 L Ð L 3 8 Power terminal 9 PE 0 (top panel) Terminal block X2 Χ2 U 1 V ¢ 2 1 🛛 • V MOTOR 3 W C 3 ₩ 4 Pf a a 4 PE +24Vdc BR BR -BR Terminal block X3 (front panel) 24 Vdc BR+ 1 3 ) ) ) ) OVdc BR STATIONARY BRAKE 0 V 4 2 BR-XЗ ΧЗ

The converter is equipped with 3 led indicators.

When power is applied to the drive (24 VDC), if the drive's electronics is working, the yellow and green leds come on. The third led (red) provides converter status information as listed below:

- if it is off, the converter is shut off without active alarms.
- if it is on, the converter is enabled. the drive is in RUN mode



- if it blinks with a pause after two series of blinks, the converter is disabled and an alarm is active. The active alarm can be identified by counting the number of blinks between the two pauses.
- if it blinks quickly and continuously, the  $I^2t$  command is active and the converter is still enabled.

Parker Hannifin S.p.A. – S.B.C. Divisi	on HID75		quick installation guide Hi-drive
International Contraction		Termina	
	1	<b>X1</b> 2 3 4 5 1	X2     Bra. Res.     X2       2     3     1     2     4
	PE L1	L2 L3 DC+ DC- U	PE
	HID100 – HID1		
X4	Fan	Termina X1	X2 Bra. Res.
X3			
	Auxiliary fan supply	1 2 3 4 L1 L2 L3 DC+	5     1     2     3     1     2       DC-     U     V     W     BR+     BR-
LED STATUS - X5	00		
X7 X9 X11			
$\mathbf{X6}$ $\mathbf{X8}$ $\mathbf{X10}$ $\mathbf{X1}$ - $\mathbf{X2}$			
X6 X8 X1 – X2		<u>X1</u>	<b>X2</b> 4
		PE	PE motor
	X5 : terminal co	onnection	
0VQ drive supply15+24V drive supply16	15 16		1 - SR drive enabling   2 + SR drive enabling
	17 🛛 🗢 知		3 SC B 4 SC A
<u>→</u> 19	18 19 19 19 10 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 11 10 10		5 IN 4
GND (DIGITAL)     20       OUT 1     21	20 20 20 20 20 20 20 20 20 20 20 20 20 2	┘ <b>∑⊚</b> ╢ 6 <b>)⊚</b> ╢ 7	6 0VA 7 MON 2
OUT 0 22		8	8 MON 1
VCC (DIGITAL) 23	23 ) • H 24 ) • H		9 0VA
GND IN 24 IN 3 25	25	<b>11</b> <b>1</b> <b>1</b>	10 – AX 11 + AX
IN 2 26		<b>John</b> 13	12 0VA
IN 1 27 IN 0 28	28 💽 🖓 🗆		13 – REF 14 + REF
X6 : "resolver" (DB9 fei	mala)	V7 : "since	s" (DB15 female)
1 PTC -		PTC - 10	Ve
2 A GND			SENSE -
3 ECC - 4 SIN -	3	A GND 12 SENSE + 13	CLK -
5 COS -	<sup>08</sup> <sub>03</sub>	CLK + 14	B - 05 05
6 PTC + 7 ECC +	o <sup>7</sup> o <sup>2</sup> of o <sup>2</sup> of o <sup>1</sup> 7	DATA + 15 B +	
8 SIN +		A +	
9 COS +	9	PTC +	
X8 : "RS422/485" (DB9 f	emale)		input" (DB9 female)
1 TX422 +		EIN A +	
2 RX422 + 3 TX422 -		EIN A - EIN B +	
4 RX422 -	0 <sup>9</sup> 0 <sup>5</sup> 0 <sup>8</sup> 0 <sup>4</sup>	EIN B -	
5 SHIELD		EIN C +	0703
6 Termination 7 N.C.	6 6 7	EIN C - 0VF	
		SHIELD	
8 N.C. 9 OV F	9	+5V F	
X10 : "encoder output" (DI	<i>,</i>		AN" (DB9 male)
1 EOUT A +	$\begin{bmatrix} 1\\ 2 \end{bmatrix}$	N.C. CANL	
2 EOUT A - 3 EOUT B +		GND CAN	
4 EOUT B -		Reserved	
5 EOUT C +	5	SHIELD	
6 EOUT C - 7 0VF		Reserved CANH	
8 Reserved		N.C.	
9 Reserved	$\frac{3}{9}$	Reserved	

Width (mm)

20

40

50

HID75

25÷50mm<sup>2</sup> (AWG4)

 $6 \div 8 \text{ Nm}$ 

BARRA PE Thickness (mm)

6/8

6/8

6/8

HID100-HID130

35÷95mm<sup>2</sup> (AWG1)

42 Nm

Length (m)

0.5

1

1.5

Model

Section

Tight. torque

Q

# 3.4 PE (Protective Earth) connections

Minimize the length of the individual ground wires by placing grounding bar as close as possible to the converters. The grounding bar must be a copper bar and must be installed in contact with the cabinet metal frame. The table shows the minimum dimensions depending on length.

Use only stranded copper wire rated for 75°C minimum.

For the model HID2 up to HID45 use e a minimum wire section of  $10 \text{ mm}^2$  for grounding.

For HID75, 100 and 130 connect the ground wire to the PE pin of X1 terminal block with the following cross sections / tightening torque :

## 3.5 Power stage supply connection

The converter can be used only in grounded TT and TN industrial networks, suitable for use on a circuit capable of delivering not more than 5000 RMS symmetrical amperes, 480V maximum.

Do not use in ungrounded networks or in networks with asymmetrical grounding (IT).





### 3.6 Motor with emergency brake

Terminal block X3 requires a dedicated 24VDC to terminals 1 and 4. Do not use the same supply of the control stage. Terminals 2 and 3 control the brake through a static relay.

Controls the output controlling the emergency brake of terminal block X3 (pin 2 and 3), managed as a command ON/OFF from drive with internal bit (b42.8).

The brake block-release function in all operating conditions must be performed by the user.

20 cm



WARNING



# 3.7 External braking resistor connection

The converter is equipped with internal braking resistor, except HID75, HID100 and HID130 that have inside the braking transistor only (see "technical data" section).

An external braking resistor can be used if an higher braking power need to be handled.

The external braking resistor must have the same  $[\Omega]$  value as the internal one. Install a bipolar thermo-magnetic switch (or a fuse pair) between the resistor and the converter (see "dynamic braking" section).

The maximum cable length for the external braking resistor is 3 meters.

For **HID2** ... **HID45** models, remove the jumper between terminals IN and BRC (X1 terminal block) and connect the external resistor between terminals RP and BRC. For **HID75**, 100 and 130 between +BR



BR+ fuse 000000000 000000000 000000000 external braking resistor



During operation, the external resistor reaches high temperatures. Let the external resistor cool down before performing any operation on it.

# 3.8 Control stage supply connection

M IMPORTANT

The drive electronics - including powering-up and switch-off operations - is supplied at 24VDC.

The 24V power supply must be exclusively dedicated to the drive power supply . Sharing the power supply with other devices (e.g. brakes, electro valves, etc.) could cause malfunctions.



# 3.9 Analogue and digital I/Os connection



### 3.10 Resolver



When the resolver is connected, no incremental encoders can be used on connector X7.

## 3.11 Sinusoidal encoder + EnDat



As far as the cable is concerned, you may use a Heidenhain cable or one with the same features. Cables without "SENSE" must not be longer than 20 metres, cables with "SENSE" shall have a maximum length of 60 metres.



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# 4 START-UP

In Its basic configuration, Hi-drive can control both synchronous permanent magnet motors (brushless) and asynchronous induction motors. The setting of Pr31 can select either of the following: **Pr31=0**, synchronous motor (default setting); **Pr31=1**, asynchronous motor.

The drive is supplied with default factory parameter settings.

See the following chapters for use and start-up.

### 4.1 Selection of motor type

The first time the converter is powered up, or following a default command, the drive indicates a "Def" condition (alarm Pr23=15).

In order to leave the drive's initial condition, the operator shall have to input the motor data. The parameters defining motor types are as follows:

The parameter	s defining motor types are as	follows:				
Pr29	Number of motor poles		N.			
Pr32	rated motor speed					
Pr33	rated motor current (ex. 2.1	5A, write 2.5)	А			
Pr46	phase-phase motor resistar	nce (ex. $1,8\Omega$ , write $1.8$ )	ohm			
Pr47	phase-phase motor inducta	nce (ex. 2.6mH, write 2.6)	mH			
Pr60	number of resolver poles		N.			
With asynchro	onous motors, the values above	e shall be supplemented with the	ne following parameters:			
Pr45	base speed	r.p.m.				
Pr48	slip	r.p.m.				
Pr49	magnetizing current	A <u>Only</u>	asynchronous motors			
Pr32	motor limit speed	r.p.m.				

After setting the parameters that identify the motor, the operator shall enter a data save command, **b42.15** (with drive disabled, b41.5=0). The drive will set the values of parameters Pr2, Pr3, Pr16, Pr17, Pr18 and Pr19 through its internal logic. The automatic calculation of the above listed parameters is performed only of the drive is in the default condition (alarm 15).

## 4.2 Setting feedback

Mod	No. of pulses revolution	Input			
Resolver	b65.15=0	b65.14=0	_		X6
SinCos + EnDat	b65.15=0	b65.14=1	Pr62=0	Pr58	$\begin{array}{c c c c c c c c c c c c c c c c c c c $
SinCos	b65.15=0	b65.14=1	Pr62=1		
Less Wiring	b65.15=0	b65.14=1	Pr62=2		
Incremental Encoder	b65.15=0	b65.14=1	Pr62=3		
SinCos + Hiperface	b65.15=0	b65.14=1	Pr62=7		
SinCos (One sin wave per pole pitch)	b65.15=0	b65.14=1	Pr62=8		
Incremental Encoder + Hall sensor	b65.15=0	b65.14=1	Pr62=10		
Incremental Encoder	b65.15=1	b65.14=0	Pr63=3	Pr59	X9

# 5 MOTIONWIZ CONFIGURATION TOOL



\* The MotionWiz program can be found on the CD rom supplied with the drive or downloaded from our website: <u>www.sbcelettronica.com</u>

# 6 ALARMS

Pr23	Alarm	Pr23	Alarm	Pr23	Alarm	
0	No alarm	6	Power module overtemperature	21	Undervoltage 24VDC	
1	Overvoltage	7	External alarm	22	Ambient over temperature	
2	Undervoltage	8	Auxiliary alarm	24	Braking transistor protection	
3	Overcurrent	10(*)	PLC check sum	25(**)	Speed loop FBK initialization error	
4	Speed loop FBK error	11(*)	Parameter check sum	26(**)	Position loop FBK initialization error	
5	PTC motor alarm	15	Default parameters	28	Position loop FBK error	
(*) reset only after default values have been loaded and saved.				$I^2T$	Current limit - "the red led is blinking	
(**)can be only reset at the next power on.			on.		continuously"	

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